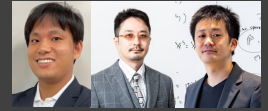


Introducing data-driven sparse sensor placement to determine rain gauge locations

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Background

Previous placement methods

MLIT: Rain gauges should be placed as many as possible to cover various precipitation patterns. (Qualitative)

Periago et al. (1998): Rain gauge locations are determined with geographical and geological data in Spain. (Quantitative, but non-generic)

Quantitative and generic placement method → **Sparse Sensor Placement (SSP)**

Sparse Sensor Placement (SSP)

Precipitation data (training period) X

Time ↓

Rain gauge locations

Dimensionality reduction

- Singular value decomposition (SVD)
- Non-negative matrix factorization (NMF)

Algorithm of SSP with SVD

- $X \approx U_r \Sigma_r V_r^T$ (SVD)
- $x = U_r a$ (a snapshot of X)
- $y = Hx = HU_r a = Ca$

For an overdetermined system, $\det(C^T C)$ is maximized.

Manohar et al. (2018), Saito et al. (2021)

The number of grids: n Time step: T

Which is better?

y: observation **H:** observation locations

Obs. operator

0	0	0	0	0	1	0
0	0	0	0	0	0	0
0	1	0	0	0	0	0
0	0	1	0	0	0	0
0	0	0	1	0	0	0
0	0	0	0	1	0	0
0	0	0	0	0	1	0

p : number of sensors

1. Dimensionality reduction

2. To extract important features for sensor placement

Data: radar/raingauge-analyzed precipitation (2006 – 2018)

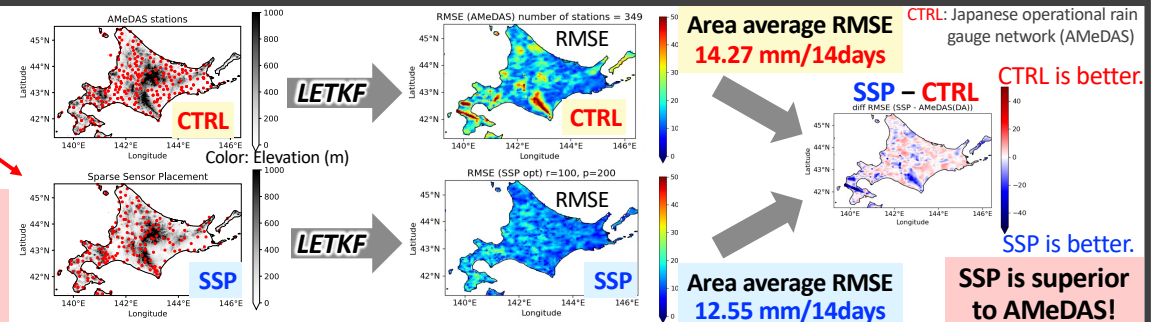
Determining H (obs. Locations) that can accurately reconstruct x from a limited number of observation

Rain gauge placement with SSP-SVD

Based on 14-day accumulated precipitation

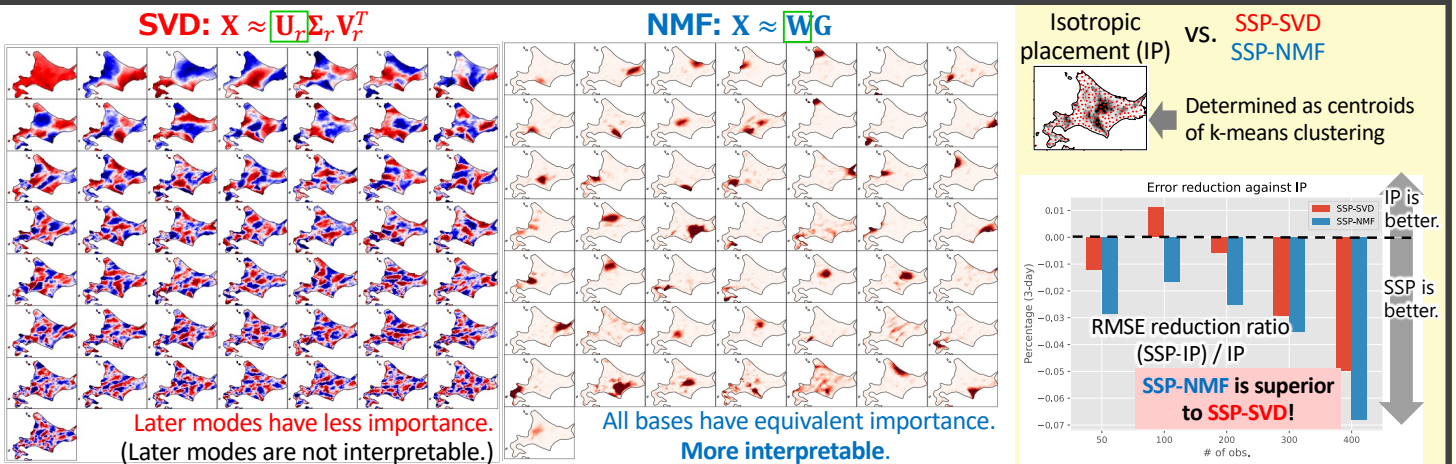
With SSP, many rain gauges are placed in mountainous areas.

SSP is a generic method!
Requiring only X .
(w/o geographical and geological data)



SSP-SVD vs. SSP-NMF

Based on 3-day accumulated precipitation



NMF works more effectively as a dimensionality reduction method for SSP than SVD!

Conclusion

- SSP is beneficial for rain gauge placement.
- Rain gauges are placed in mountainous areas by SSP.
- NMF decomposes to physically interpretable patterns.
- NMF is superior to SVD for SSP.