

Ensemble Kalman Filtering with perturbed rainfall for improving flush flood predictions by a Rainfall-Runoff-Inundation Model

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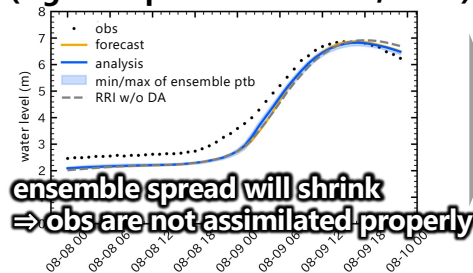
Background and Objective

Objective: Assimilate simulated water levels with EnKF to improve forecast accuracy

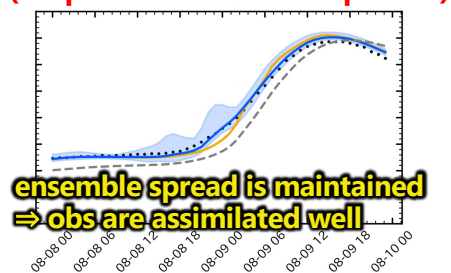
What is the appropriate covariance inflation method when applying EnKF to a non-chaotic hydrological model?

- The output of RRI being more influenced by the current rainfall, rather than the initial state

with typical inflations
(e.g. multiplicative inflation, RTPP)

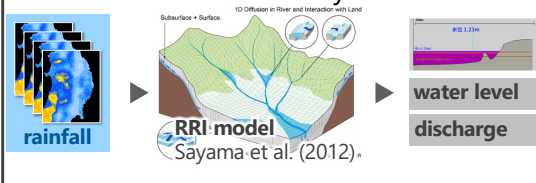


with proposed inflations
(i.e. perturb to rainfall & params)



Rainfall-Runoff-Inundation (RRI) Model

Two-dimensional model capable of simulating rainfall-runoff and flood inundation simultaneously



Method & Experiment Settings

Expand the spread of RRI output by adding per-ensemble uncertainty to the model

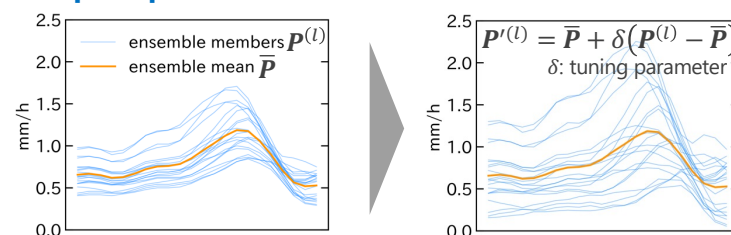
① Perturb to rainfall

Using ensemble forecast rainfall distribution
• Meso-scale ensemble prediction system (MEPS)

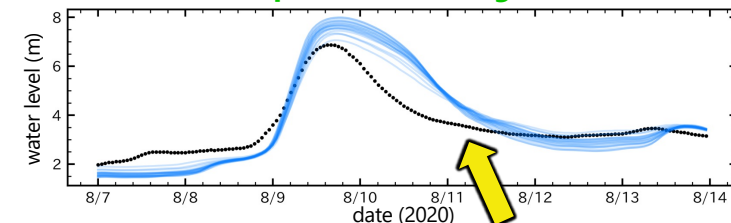
② Perturb to model parameter

• Manning's roughness coefficient (flow velocity)
• Effective porosity (infiltration into the ground)

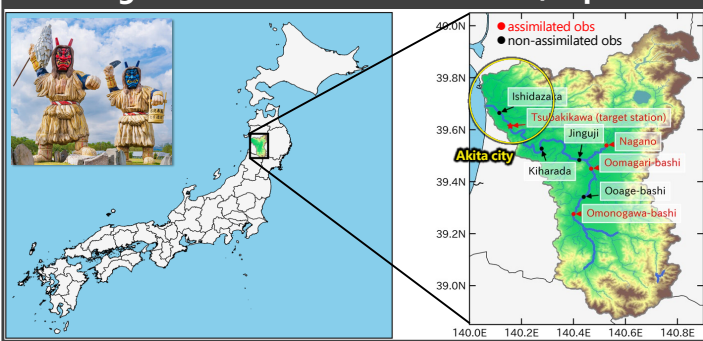
① Expand perturbation of ensemble forecast rainfall



② Perturb to model parameters change simulated results



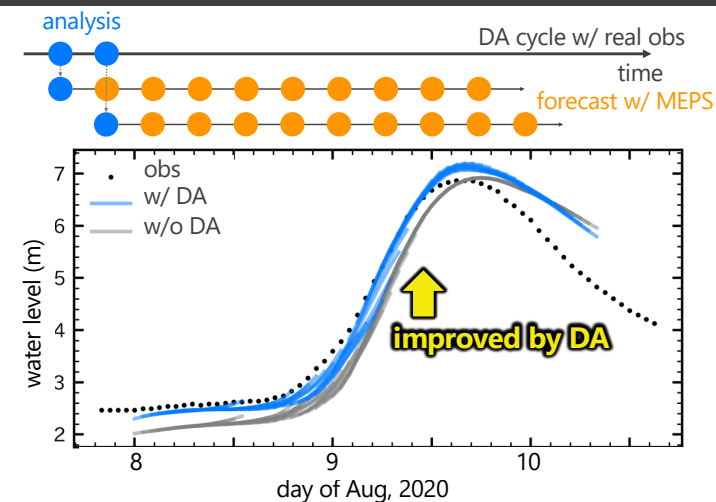
Target Basin: Omono River in Akita, Japan



Experiment Settings

- Serial EnSRF (21 members)
- Assimilate hourly obs at 4 stations

Result: 9hr Forecast Simulation



Summary

What we did

- We applied EnKF for RRI to adjust model state variables with operational water-level observations.
- The assimilation was stabilized by perturbing the input rainfall intensity and model soil parameters for each ensemble member.
- Our experiments showed that predicted water level was improved at both observed and unobserved stations compared to the RRI simulations without assimilation.

Future work

- To find the optimal parameter combinations for the inflation methods proposed in this study.