

# Physics-inspired GNNs

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*University of Oxford*



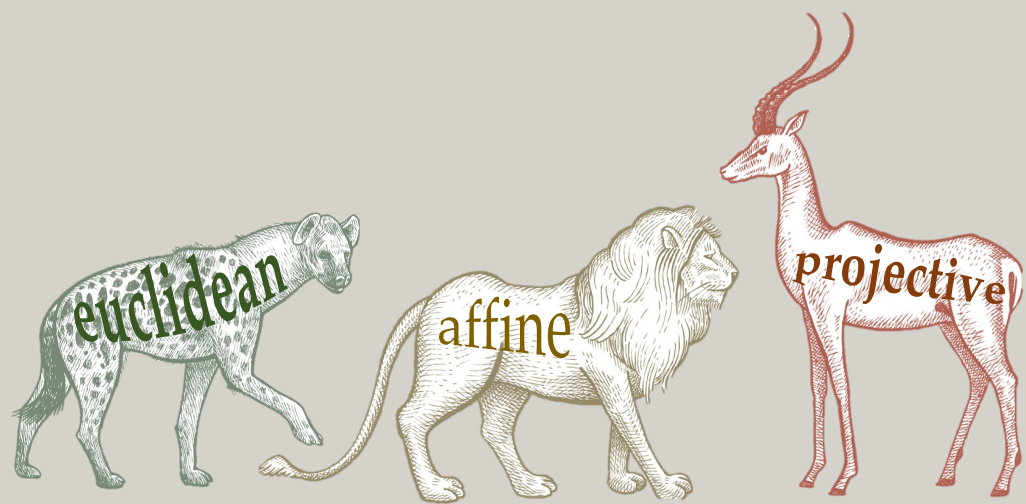
“Symmetry, as wide or as narrow as you may define its meaning, is one idea by which man through the ages has tried to comprehend and create order, beauty, and perfection”



**Hermann Weyl**

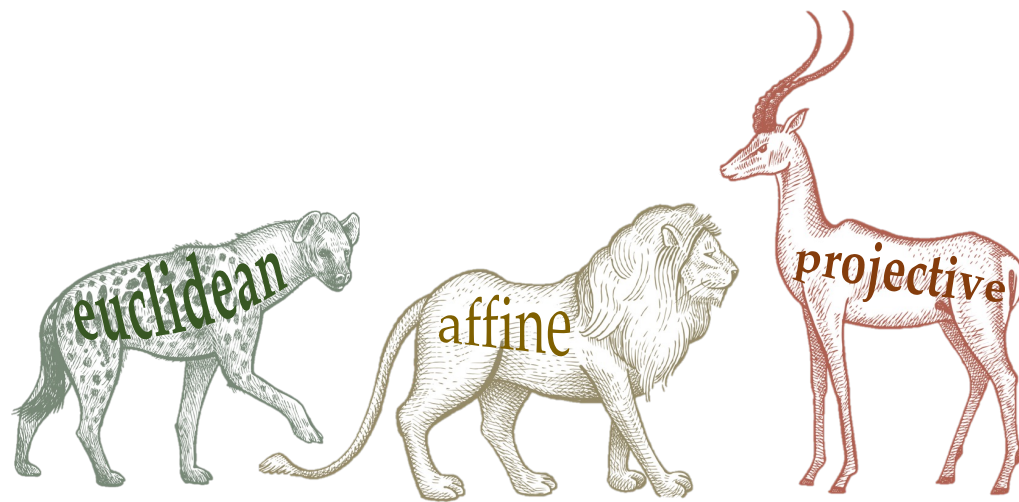
XIX century



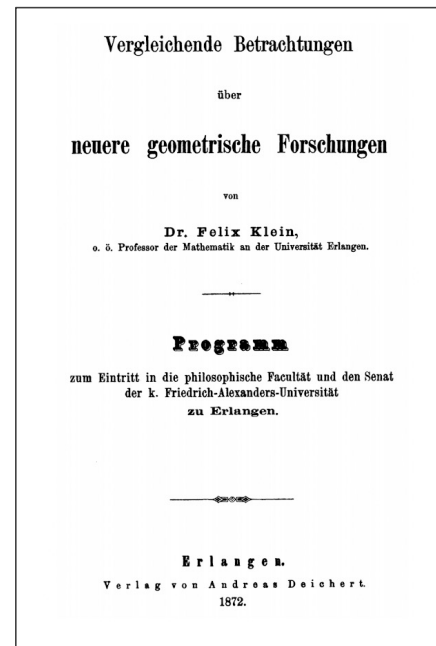




# The Erlangen Programme



**Geometry = space + transformation group**



**Felix Klein**

# Cultural Impact in Mathematics



E. Beltrami

1868



E. Cartan

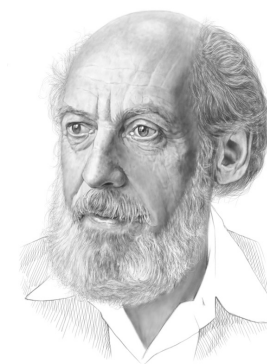
1920s

**GENERAL THEORY OF NATURAL EQUIVALENCES**  
BY  
SAMUEL EILENBERG AND SAUNDERS MACLANE

CONTENTS

	Page
Introduction .....	231
I. Categories and functors .....	237
1. Definition of categories .....	237
2. Examples of categories .....	239
3. Functors in two arguments .....	241
4. Examples of functors .....	242
5. Slicing of functors .....	245
6. Foundations .....	246
II. Natural equivalences of functors .....	248
7. Transformations of functors .....	248
8. Categories of functors .....	250
9. Composition of functors .....	250
10. Examples of transformations .....	251
11. Groups as categories .....	256
12. Construction of functors by transformations .....	257
13. Combination of the arguments of functors .....	258
III. Functors and groups .....	260
14. Subfunctors .....	260
15. Quotient functors .....	262
16. Examples of subfunctors .....	263
17. The isomorphism theorems .....	265
18. Direct products of functors .....	267
19. Characters .....	270
IV. Partially ordered sets and projective limits .....	272
20. Quasi-ordered sets .....	272
21. Direct systems as functors .....	273
22. Inverse systems as functors .....	276
23. The categories $\mathfrak{Dir}$ and $\mathfrak{Inv}$ .....	277
24. The lifting principle .....	280
25. Functors which commute with limits .....	281
V. Applications to topology .....	283
26. Complexes .....	283
27. Homology and cohomology groups .....	284
28. Duality .....	287
29. Universal coefficient theorems .....	288
30. Čech homology groups .....	290
31. Miscellaneous remarks .....	292
Appendix. Representations of categories .....	292

**Introduction.** The subject matter of this paper is best explained by an example, such as that of the relation between a vector space  $L$  and its "dual"  
Presented to the Society, September 8, 1942; received by the editors May 15, 1945.



S. Eilenberg



S. Mac Lane

1945

## Category Theory

Portraits: Ihor Gorskyi

# *New Physics*



**H. Poincaré**

1904



**H. Minkowski**

1907



**E. Noether**

1918



**H. Weyl**

1929



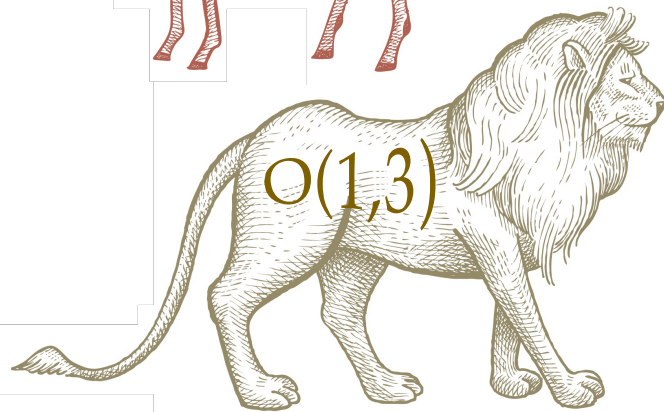
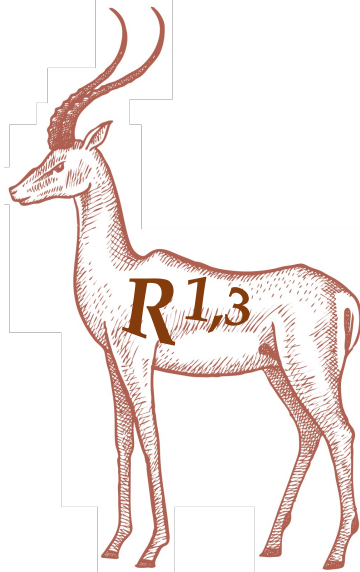
**C. N. Yang**

1954

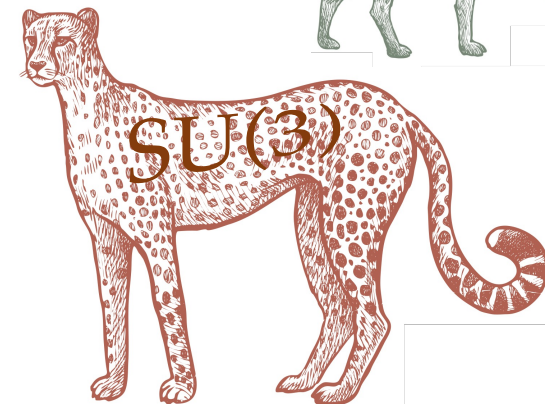


**R. L. Mills**





External symmetry



Internal symmetry

“It is only slightly overstating the case to say that  
Physics is the study of symmetry”

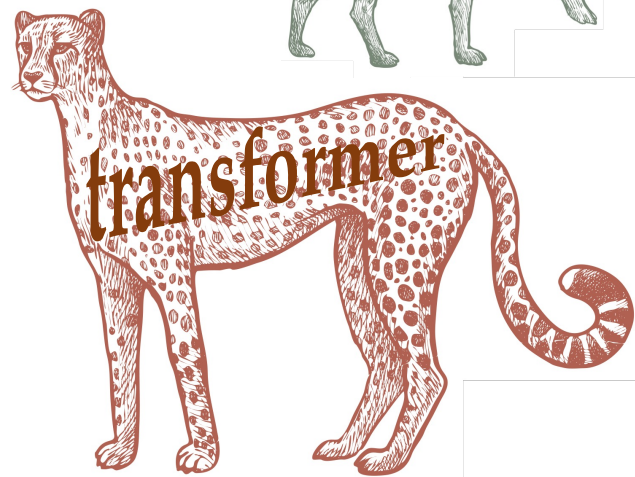
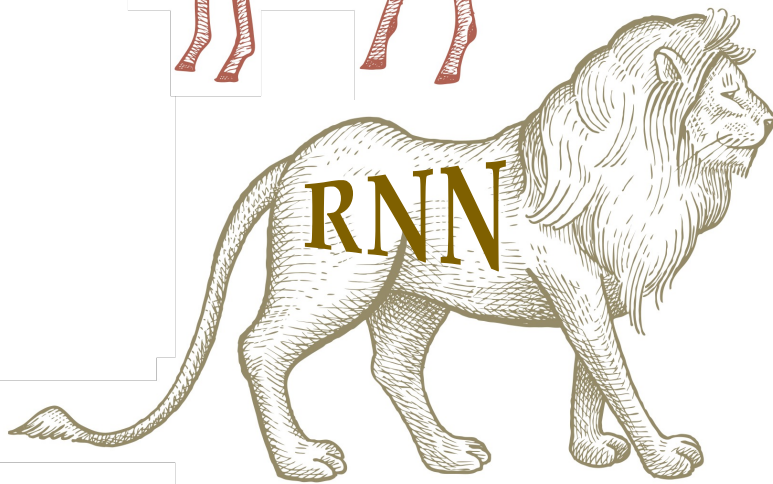
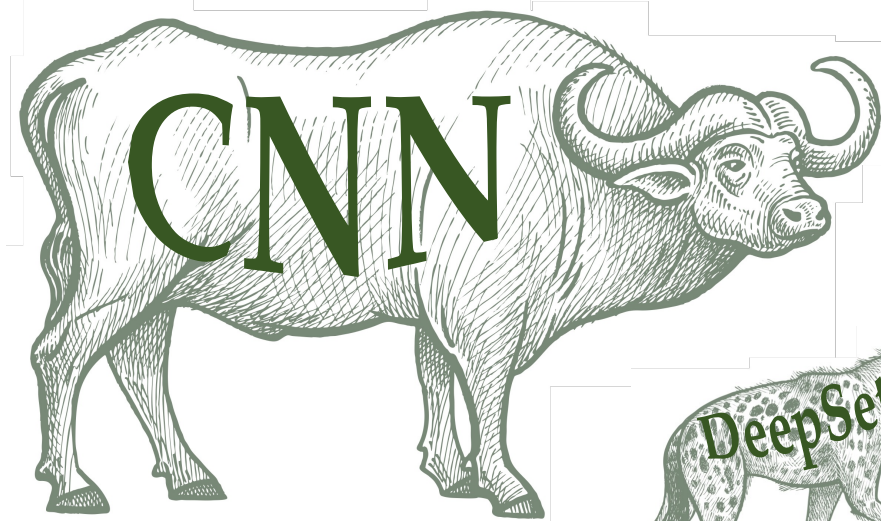
— “More is different”



**P. Anderson**

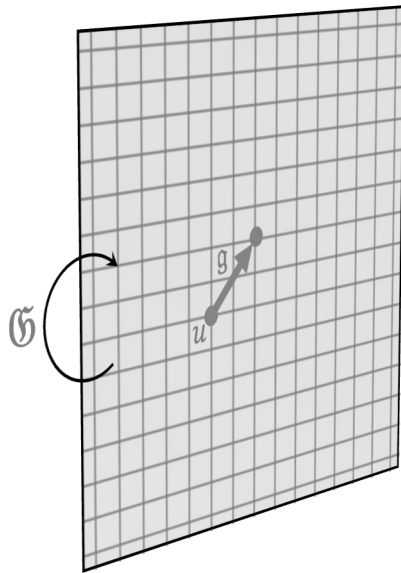
?





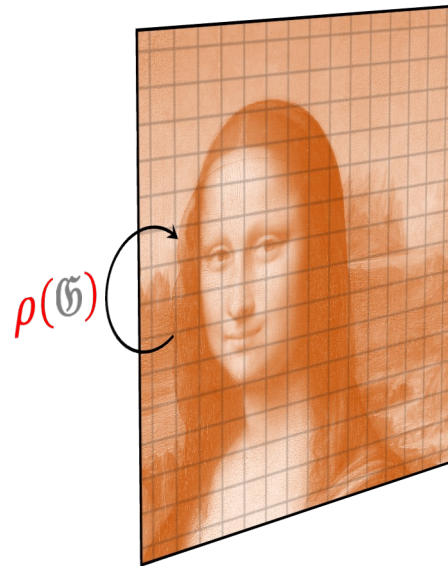
# Geometric Deep Learning Blueprint

domain  $\Omega$



symmetry group  $\mathcal{G}$

signals  $\mathcal{X}(\Omega)$



group representation  $\rho(\mathcal{G})$

functions  $\mathcal{F}(\mathcal{X}(\Omega))$



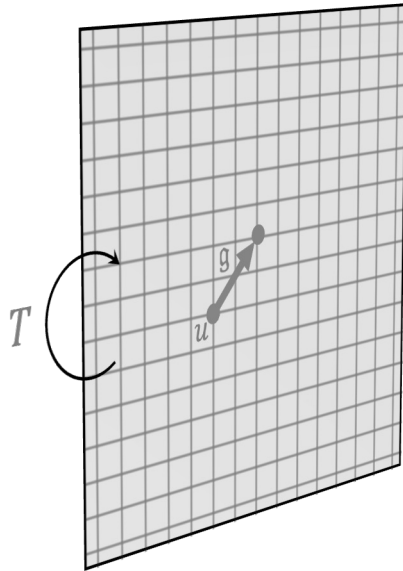
**Invariance / Equivariance**

$$f(\rho(g)x) = f(x)$$

$$f(\rho(g)x) = \rho(g)f(x)$$

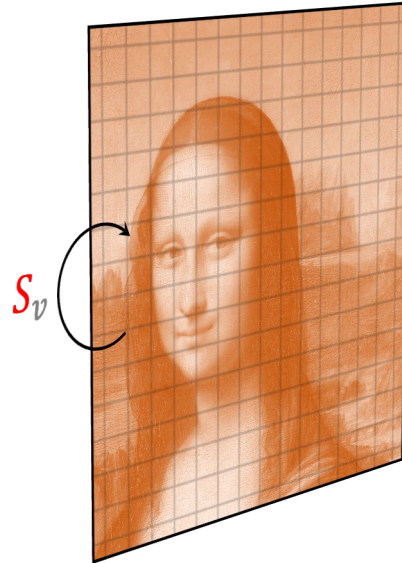
# Example: Convolutional Neural Networks

Plane  $\mathbb{R}^2$



Translation group  $T(2)$

images  $\mathcal{X}(\mathbb{R}^2)$



Shift operator  $S$

$$S_v x(u) = x(u - v)$$

functions  $\mathcal{F}(\mathcal{X}(\Omega))$



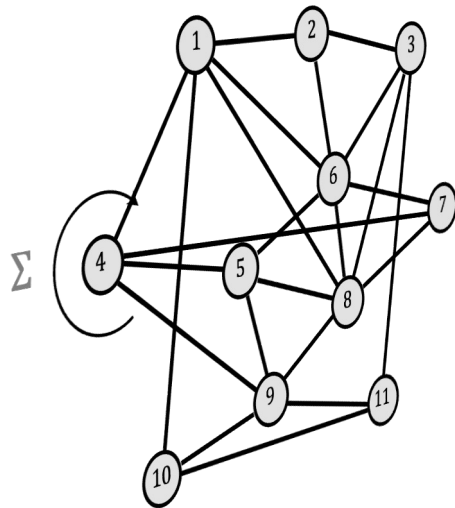
Convolutional layer

$$(Sx \star y) = S(x \star y)$$



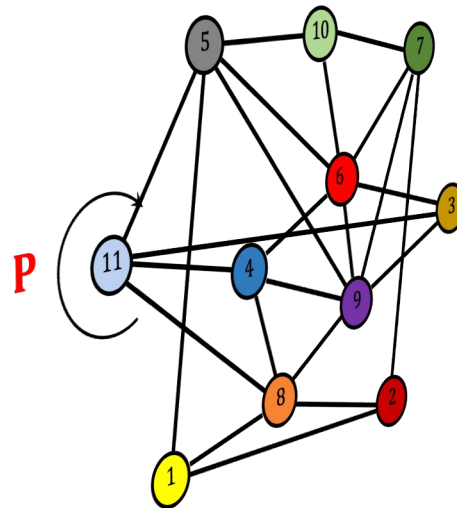
# Example: Graph Neural Networks

Graph  $G = (V, E)$



Permutation group  $\Sigma_n$

Node features  $\mathcal{X}(G)$



Permutation matrix  $\mathbf{P}$

$$\mathbf{P}\mathbf{X} = (x_{\pi^{-1}(i),j})$$

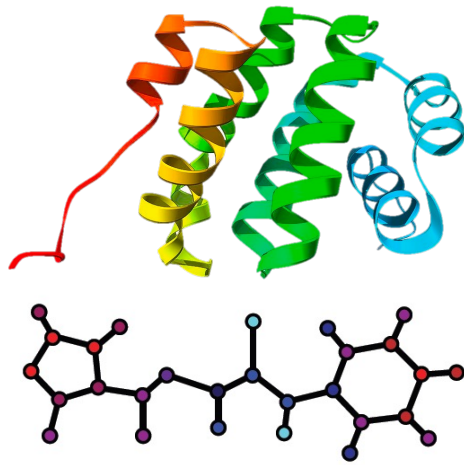
functions  $\mathcal{F}(\mathcal{X}(\Omega))$



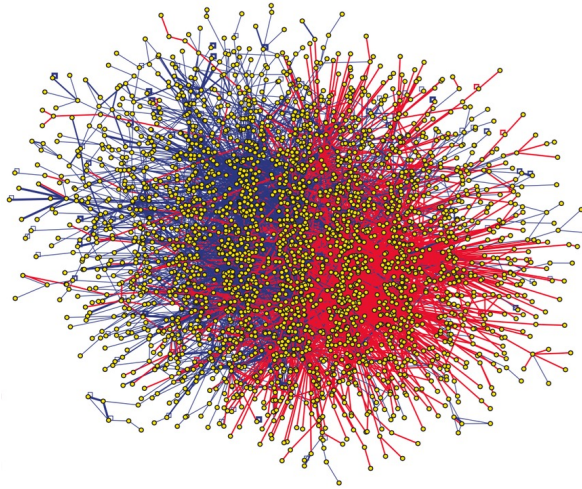
Message passing

$$\mathbf{F}(\mathbf{P}\mathbf{X}, \mathbf{P}\mathbf{A}\mathbf{P}^T) = \mathbf{P}\mathbf{F}(\mathbf{X}, \mathbf{A})$$

*Graphs = Systems of Relations and Interactions*



**Molecules**

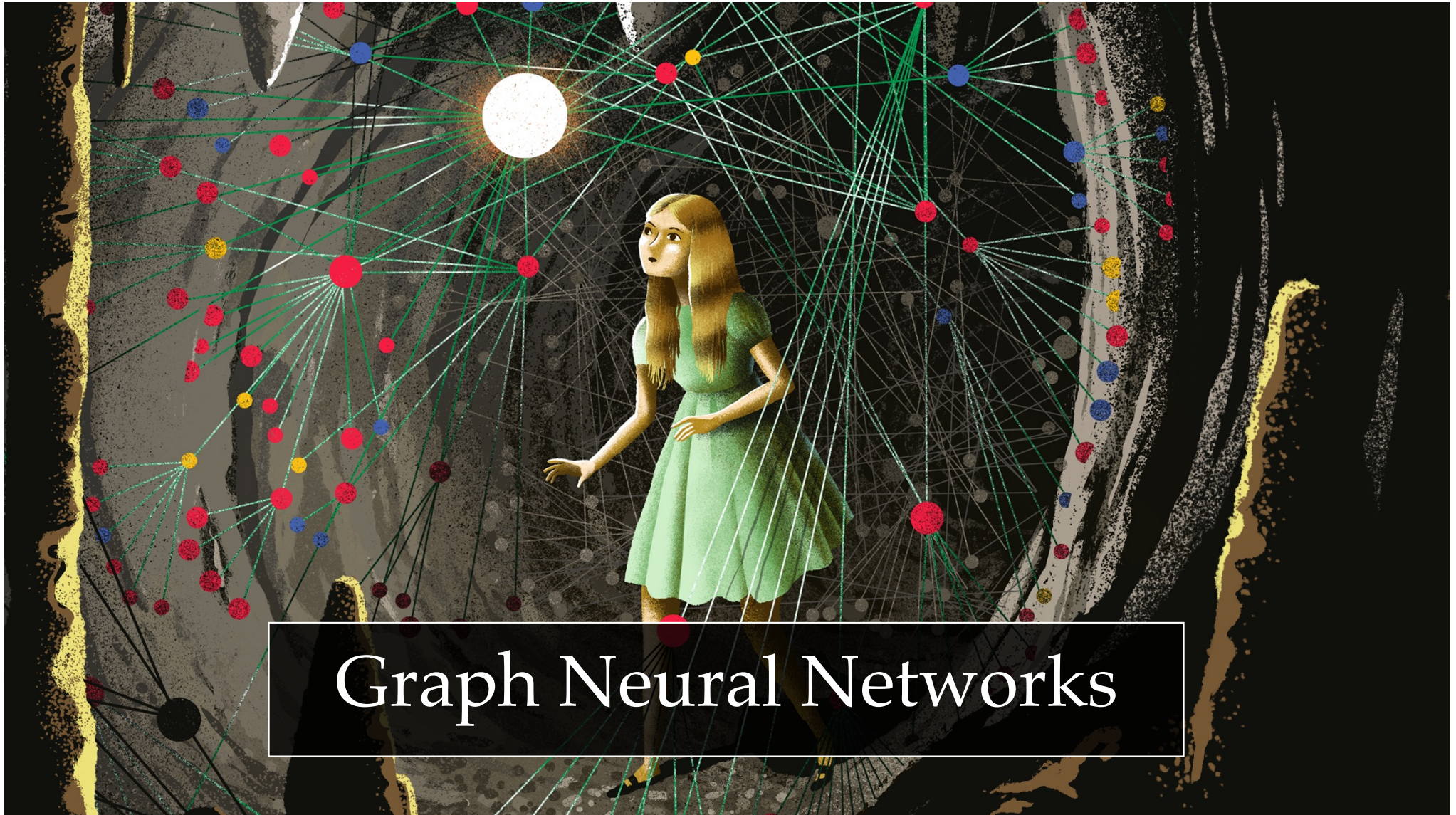


**Interactomes**



**Social networks**

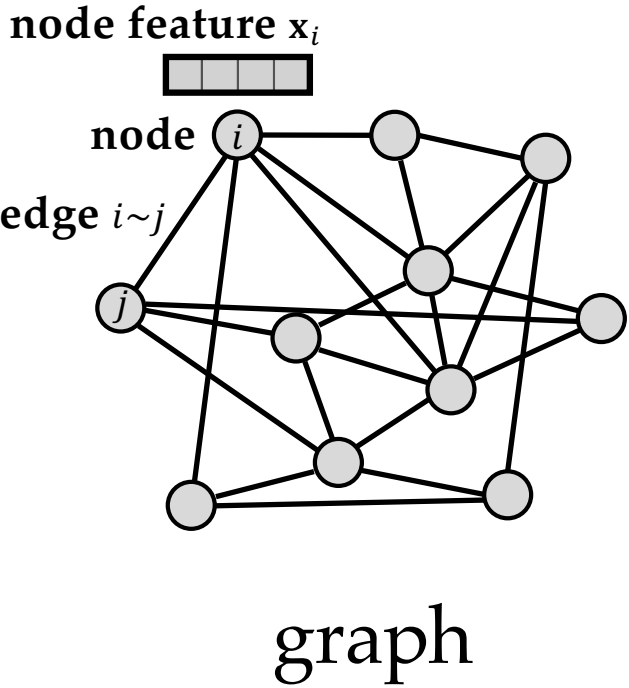




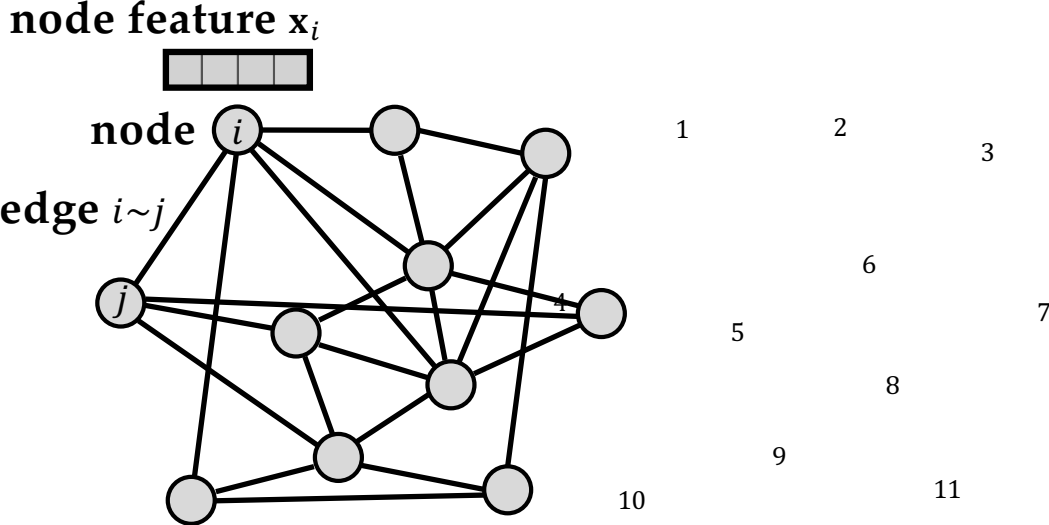
# Graph Neural Networks



# Graphs: The Basics



# Key Structural Properties of Graphs



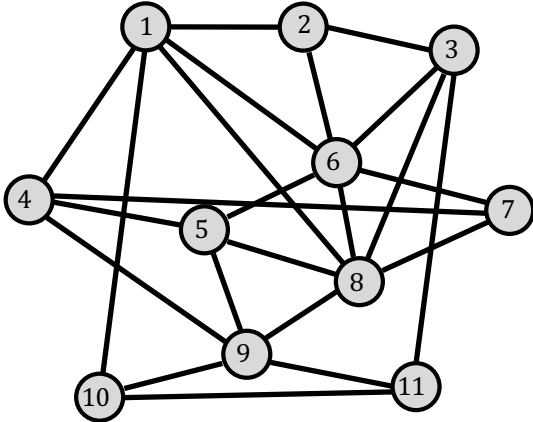
arbitrary graph ordering of nodes

# Key Structural Properties of Graphs

Feature matrix  $n \times d$

1			
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			

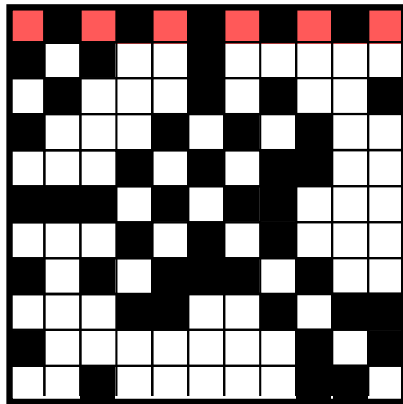
**X**



arbitrary ordering of nodes

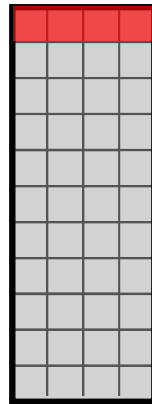
# Key Structural Properties of Graphs

Adjacency  
matrix  $n \times n$

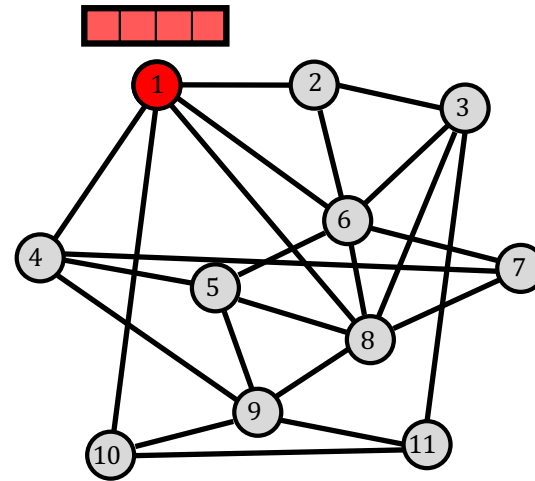


**A**

Feature  
matrix  $n \times d$



**X**

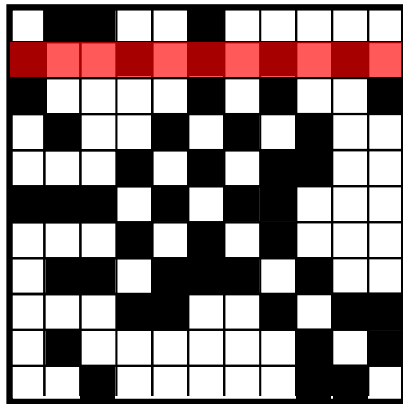


arbitrary ordering of nodes



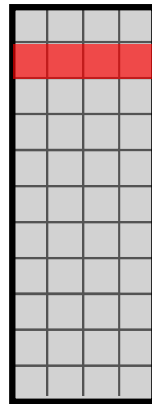
# Key Structural Properties of Graphs

Adjacency  
matrix  $n \times n$

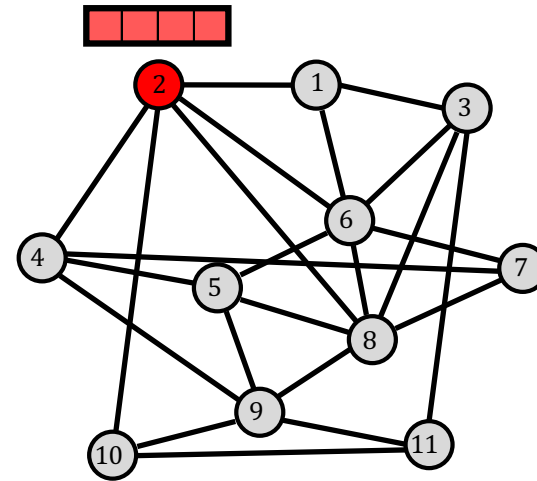


$PAP^T$

Feature  
matrix  $n \times d$



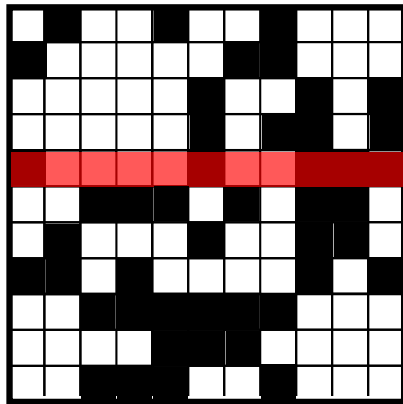
$PX$



arbitrary ordering of nodes

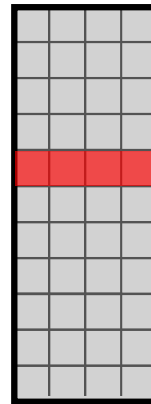
# Key Structural Properties of Graphs

Adjacency  
matrix  $n \times n$

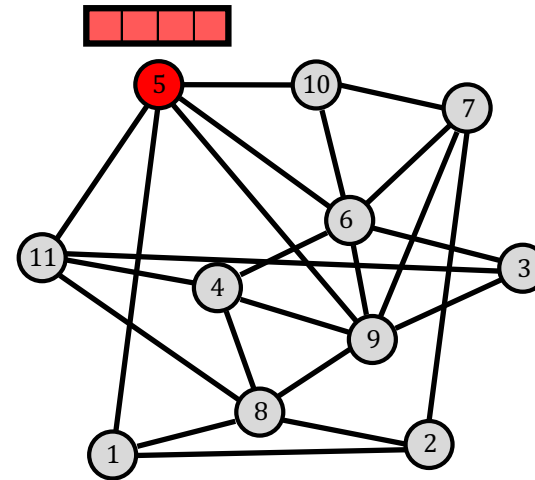


$PAP^T$

Feature  
matrix  $n \times d$



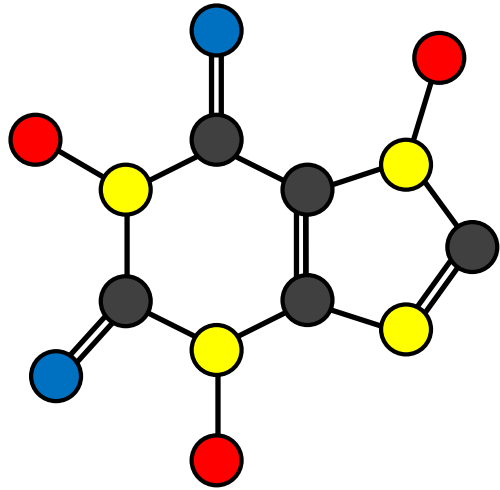
$PX$



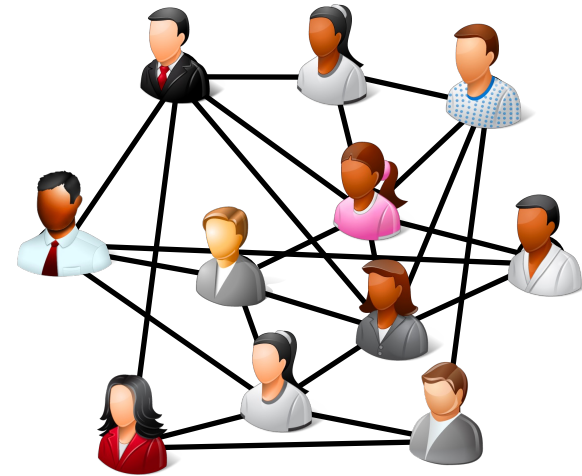
arbitrary ordering of nodes

*$n!$  permutations*

## *Invariant vs Equivariant tasks*



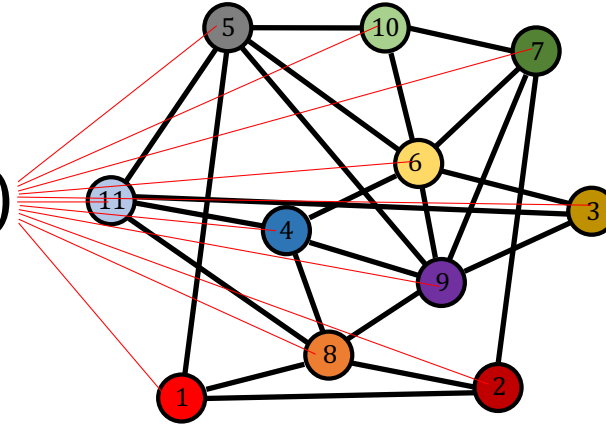
water solubility?



who is a spammer?

# *Invariant Graph Functions*

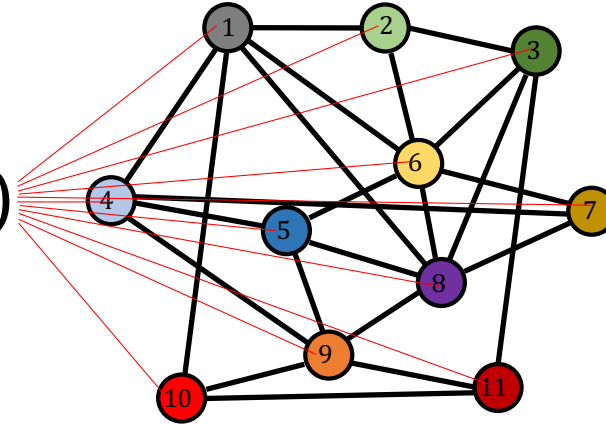
graph function  $f(\mathbf{X}, \mathbf{A})$





# *Invariant Graph Functions*

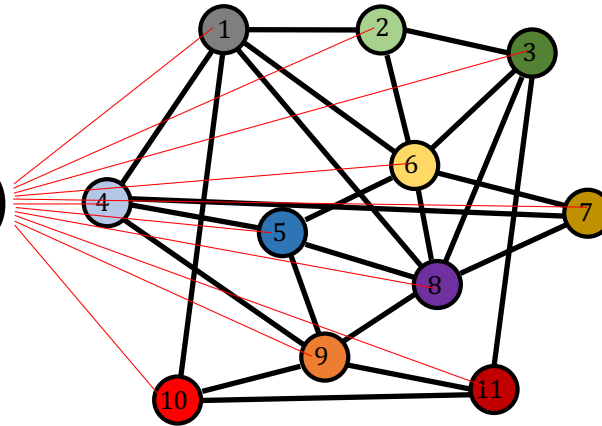
graph function  $f(\mathbf{X}, \mathbf{A})$



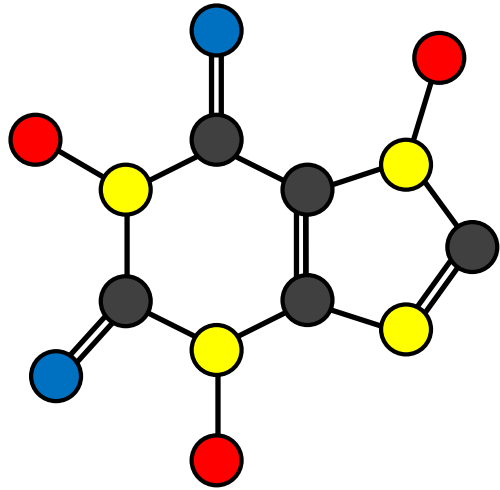
# *Invariant Graph Functions*

permutation-invariant

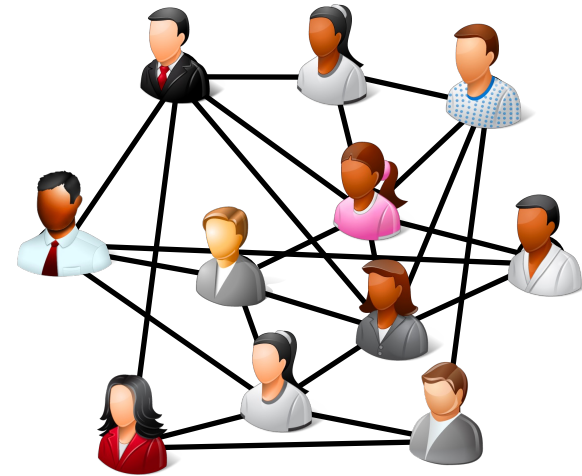
$$f(\mathbf{PX}, \mathbf{PAP}^\top) = f(\mathbf{X}, \mathbf{A})$$



## *Invariant vs Equivariant tasks*



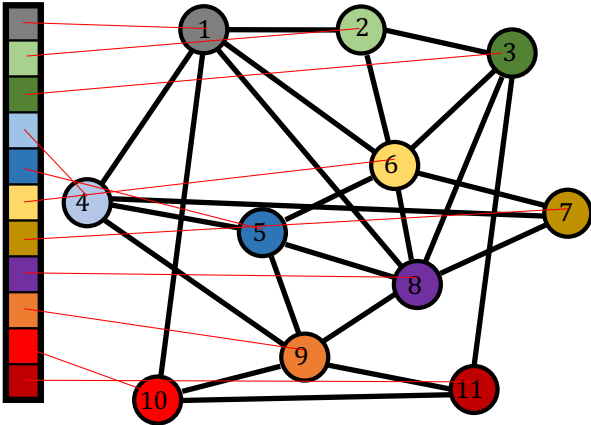
water solubility?



who is a spammer?

# *Equivariant Graph Functions*

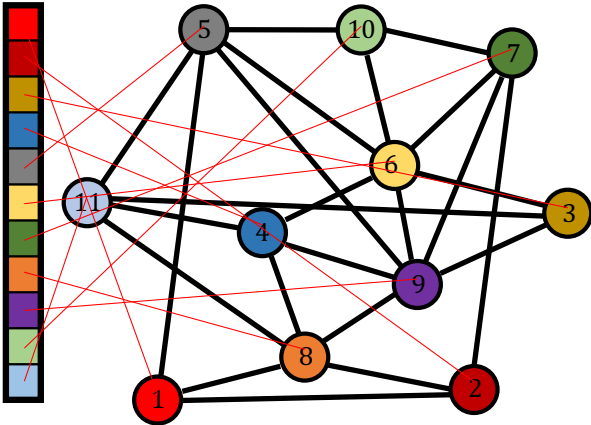
node function  $\mathbf{F}(\mathbf{X}, \mathbf{A})$





*Equivariant Graph Functions*

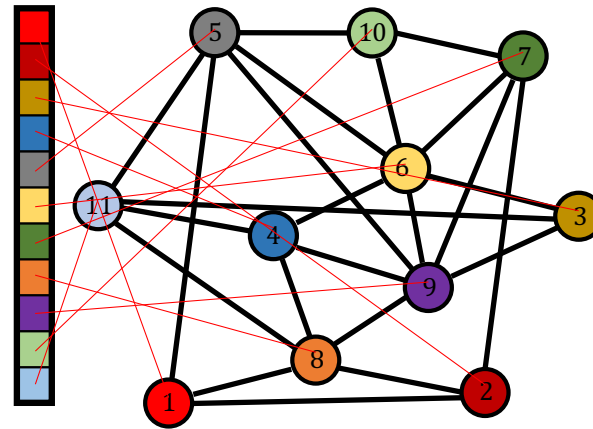
node function  $\mathbf{F}(\mathbf{X}, \mathbf{A})$



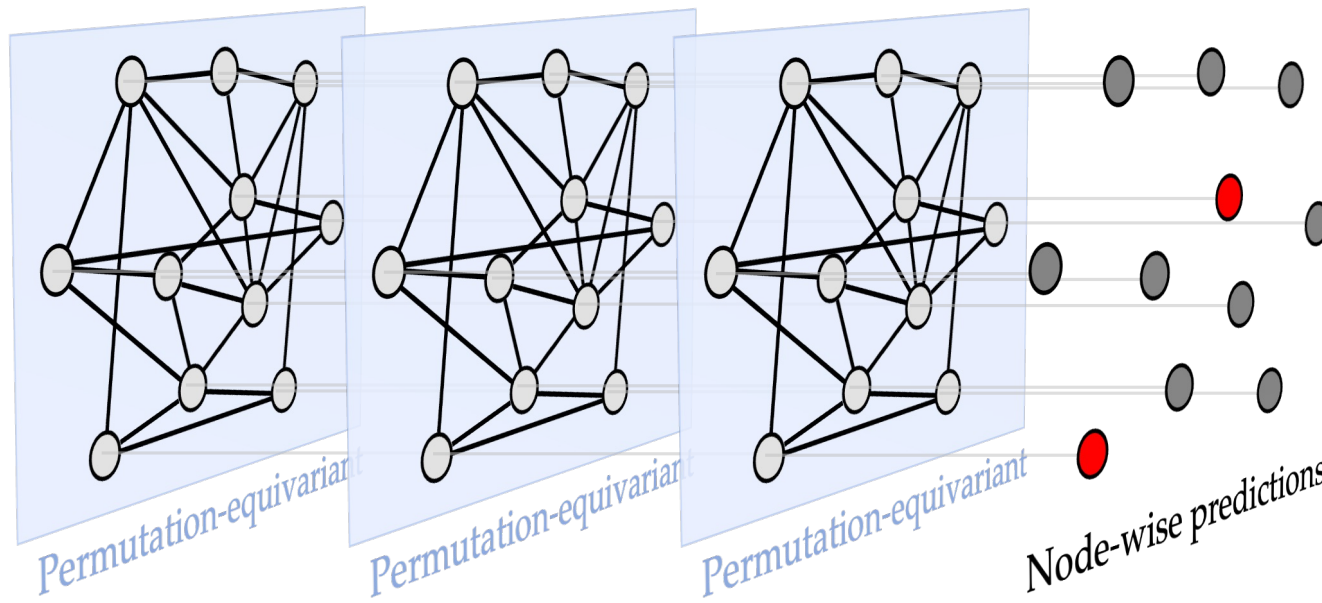
# *Equivariant Graph Functions*

permutation-equivariant

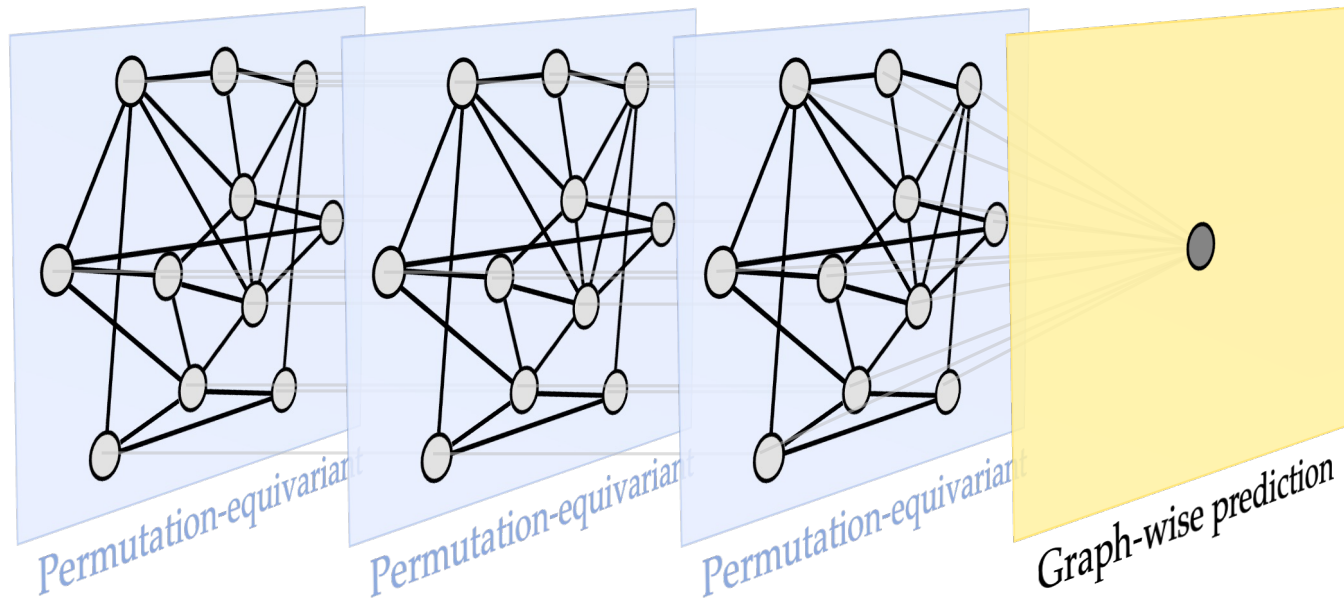
$$\mathbf{F}(\mathbf{P}\mathbf{X}, \mathbf{P}\mathbf{A}\mathbf{P}^\top) = \mathbf{P}\mathbf{F}(\mathbf{X}, \mathbf{A})$$



# Graph Neural Networks: Node tasks



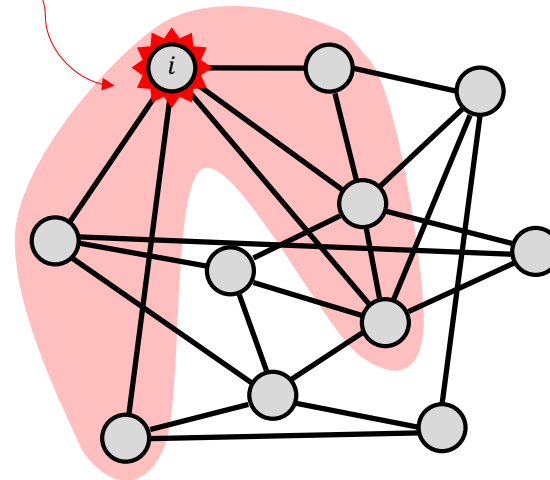
# Graph Neural Networks: Graph tasks





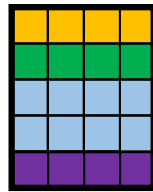
# Neighbour Aggregation

neighbourhood  
 $\mathcal{N}_i = \{j: i \sim j\}$



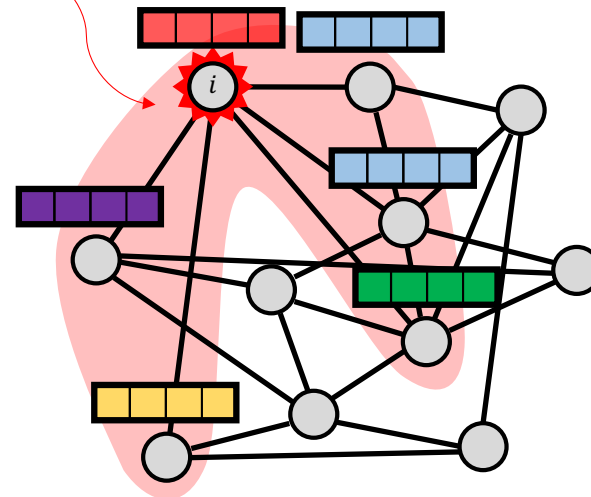
# Neighbour Aggregation

multiset of  
neighbour features



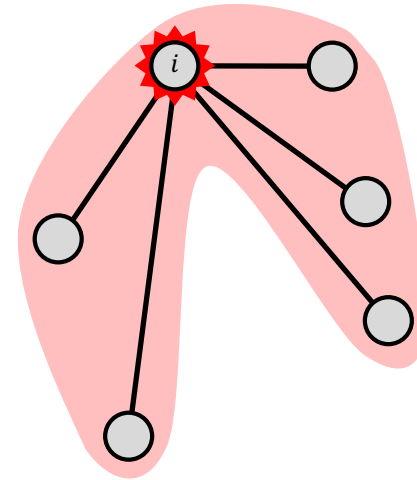
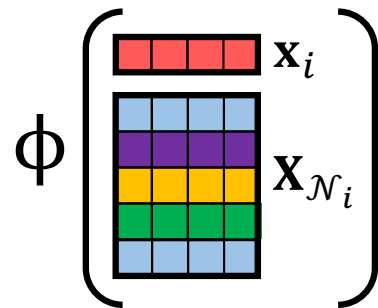
$$\mathbf{X}_{\mathcal{N}_i} = \{ \mathbf{x}_{j \in \mathcal{N}_i} \}$$

neighbourhood  
 $\mathcal{N}_i = \{j: i \sim j\}$



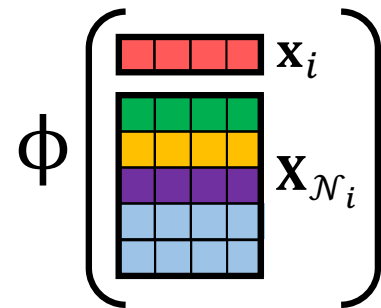
# Neighbour Aggregation

local function

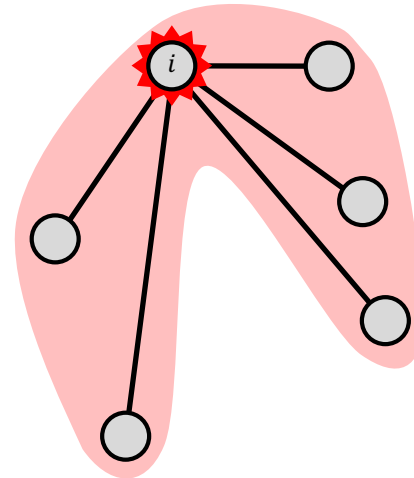


# Neighbour Aggregation

local function



permutation invariant



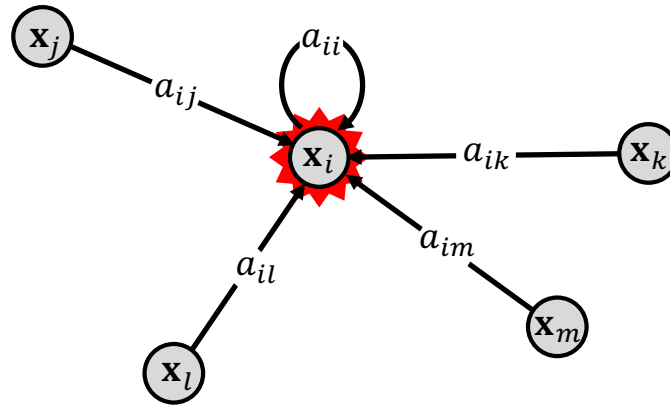
## *GNN Layer*

$$\mathbf{F}(\mathbf{X}, \mathbf{A}) = \begin{pmatrix} -\phi(\mathbf{x}_1, \mathbf{X}_{\mathcal{N}_1}) - \\ \vdots \\ -\phi(\mathbf{x}_i, \mathbf{X}_{\mathcal{N}_i}) - \\ \vdots \\ -\phi(\mathbf{x}_n, \mathbf{X}_{\mathcal{N}_n}) - \end{pmatrix}$$

permutation equivariant

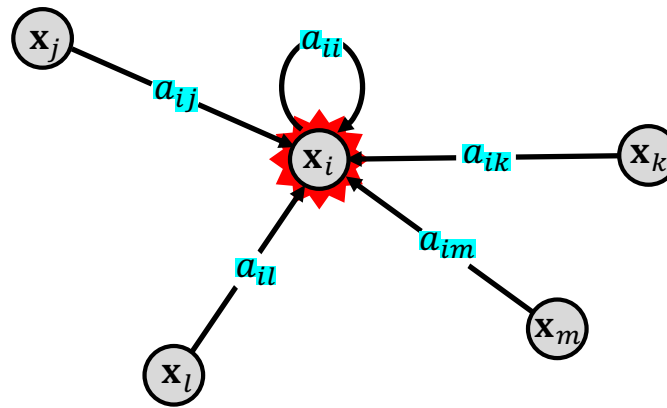


# Convolutional GNNs



$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \psi(\mathbf{x}_j) \right)$$

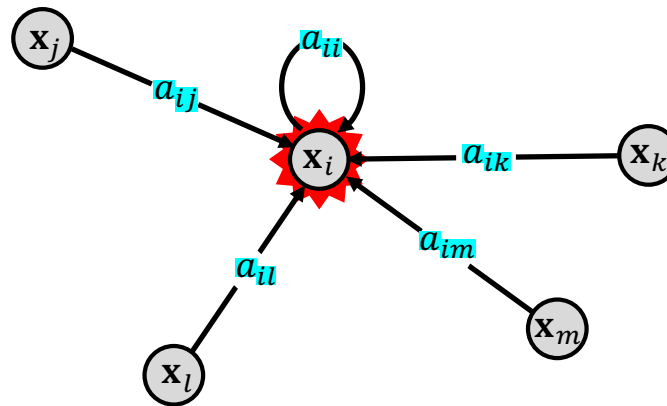
# Convolutional GNNs



$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \psi(\mathbf{x}_j) \right)$$

graph adjacency

# Convolutional GNNs



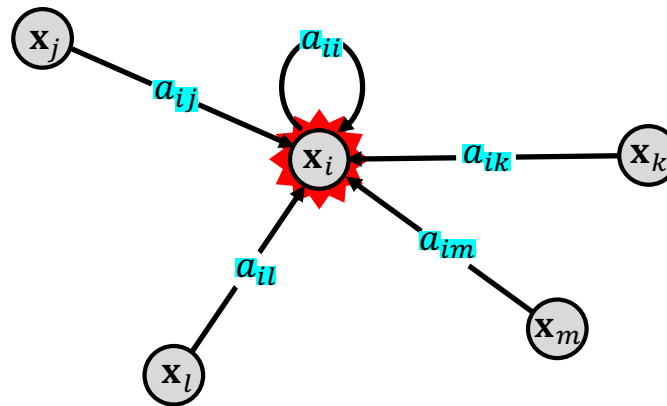
$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \psi(\mathbf{x}_j) \right)$$

nonlinear activation

graph adjacency

node-wise transformation

# Convolutional GNNs



$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \mathbf{W} \mathbf{x}_j \right)$$

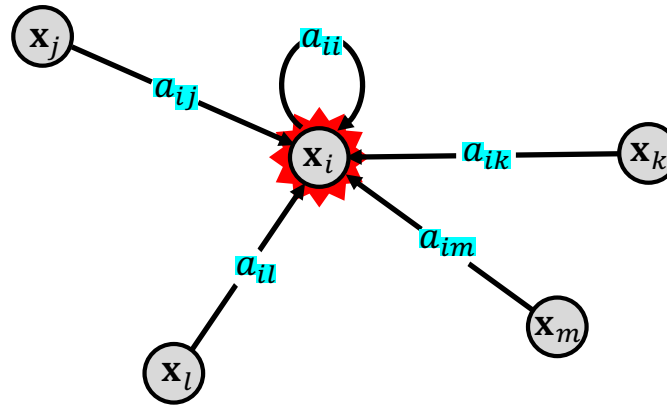
nonlinear activation

graph adjacency

node-wise linear transformation

# Convolutional GNNs

- Simplest GNN
- Highly scalable
- Industrial use cases
- Folklore: works only on **homophilic graphs**



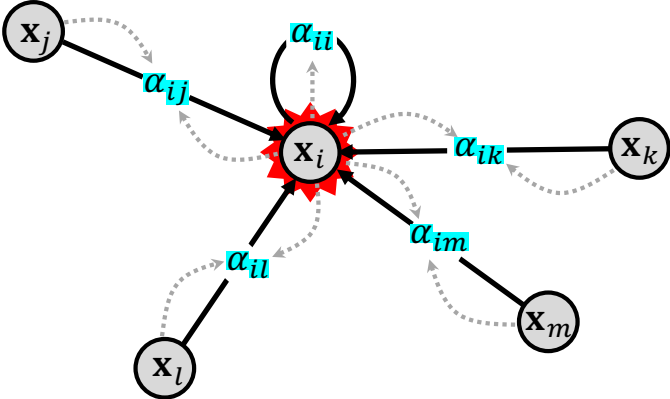
$$\mathbf{X} \leftarrow \sigma(\mathbf{A}\mathbf{X}\mathbf{W})$$

diffusion  $n \times n$       channel mixing  $d \times d$

Defferdard et al. 2016; Kipf, Welling 2016 (GCN)  
Rossi, Frasca et B 2020 (SIGN); Ying et al. 2018 (PinSAGE)



# Attentional GNNs

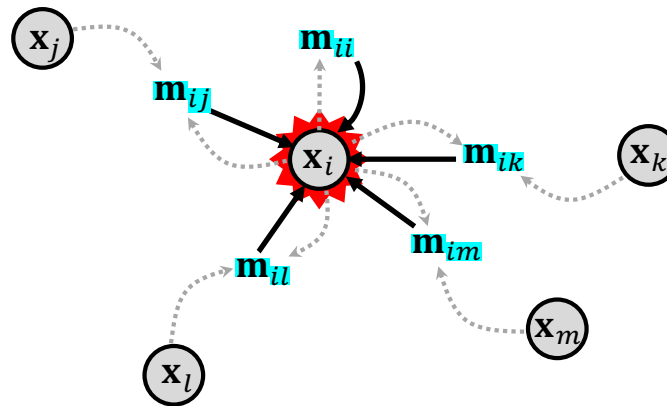


$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} \alpha_{ij}(\mathbf{x}_i, \mathbf{x}_j) \psi(\mathbf{x}_j) \right)$$

learnable attention weights

Monti et al. 2017; Veličković et al. 2018 (GAT)

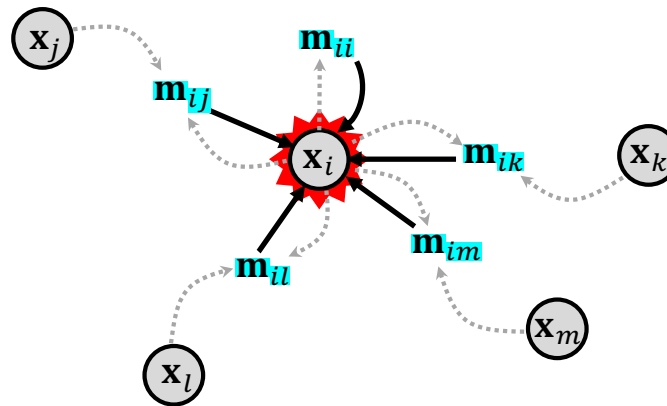
# Message-Passing GNNs



$$\mathbf{x}_i \leftarrow \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} \psi(\mathbf{x}_i, \mathbf{x}_j) \right)$$

message from  
node  $j$  to node  $i$

## Message-Passing GNNs

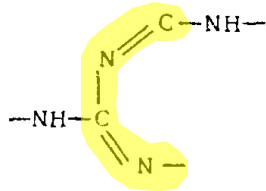
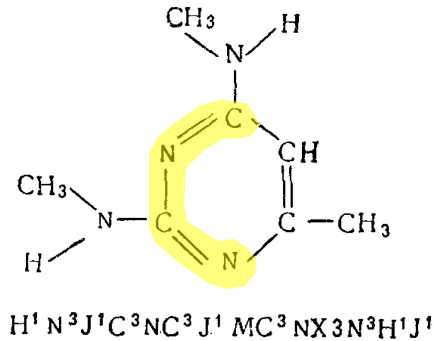


Message Passing GNNs with **injective aggregation** are equivalent to Weisfeiler-Lehman graph isomorphism test

# Weisfeiler-Lehman Test & Chemical precursors of GNNs



George Vlăduț



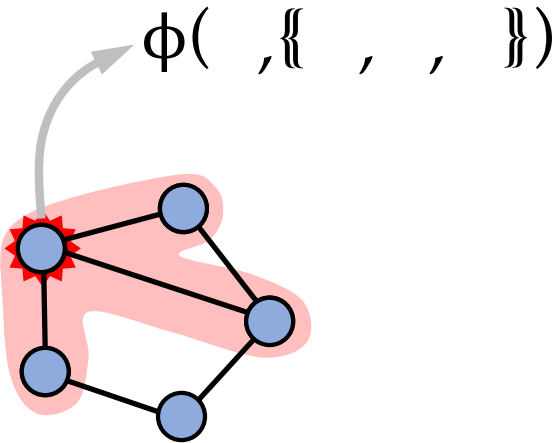
Andrey Lehman



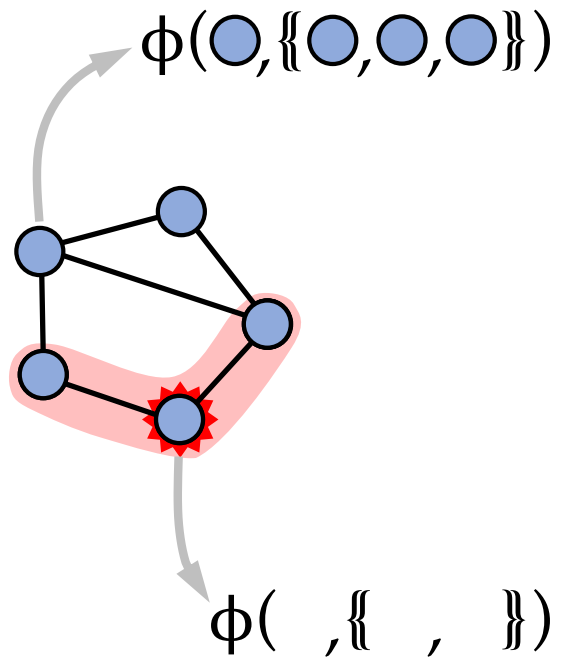
Boris Weisfeiler

Vlăduț et al. 1959; Weisfeiler, Lehman 1968

# Weisfeiler-Lehman Test

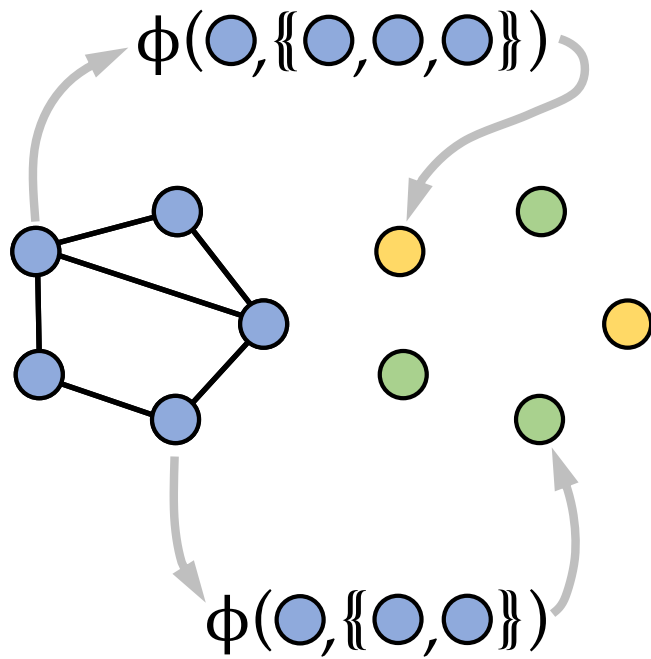


# Weisfeiler-Lehman Test

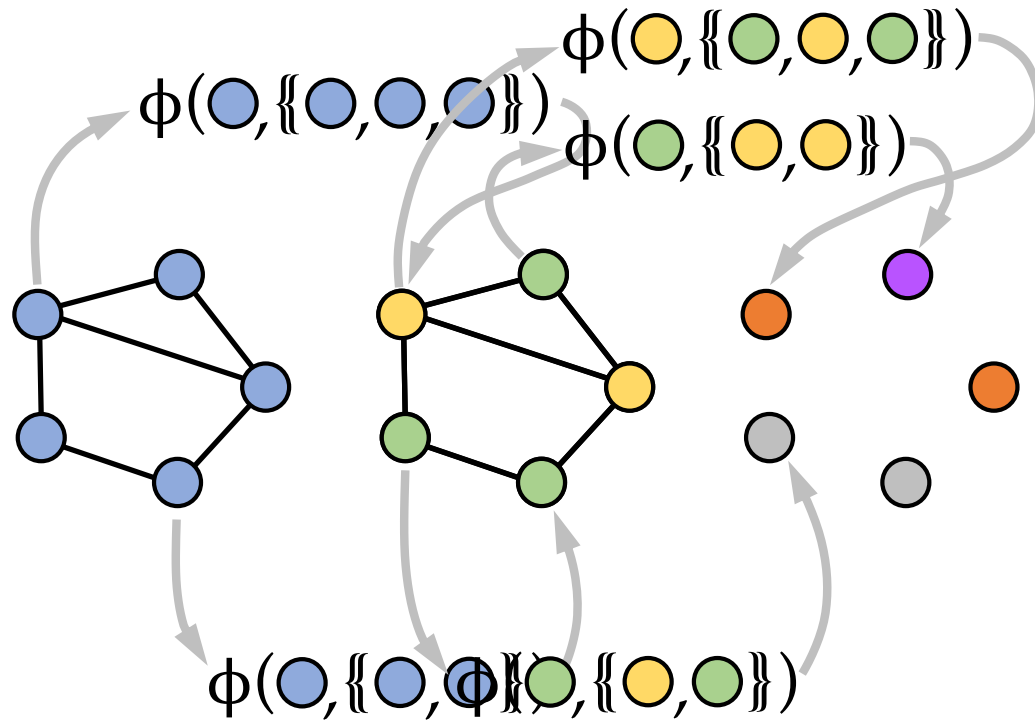




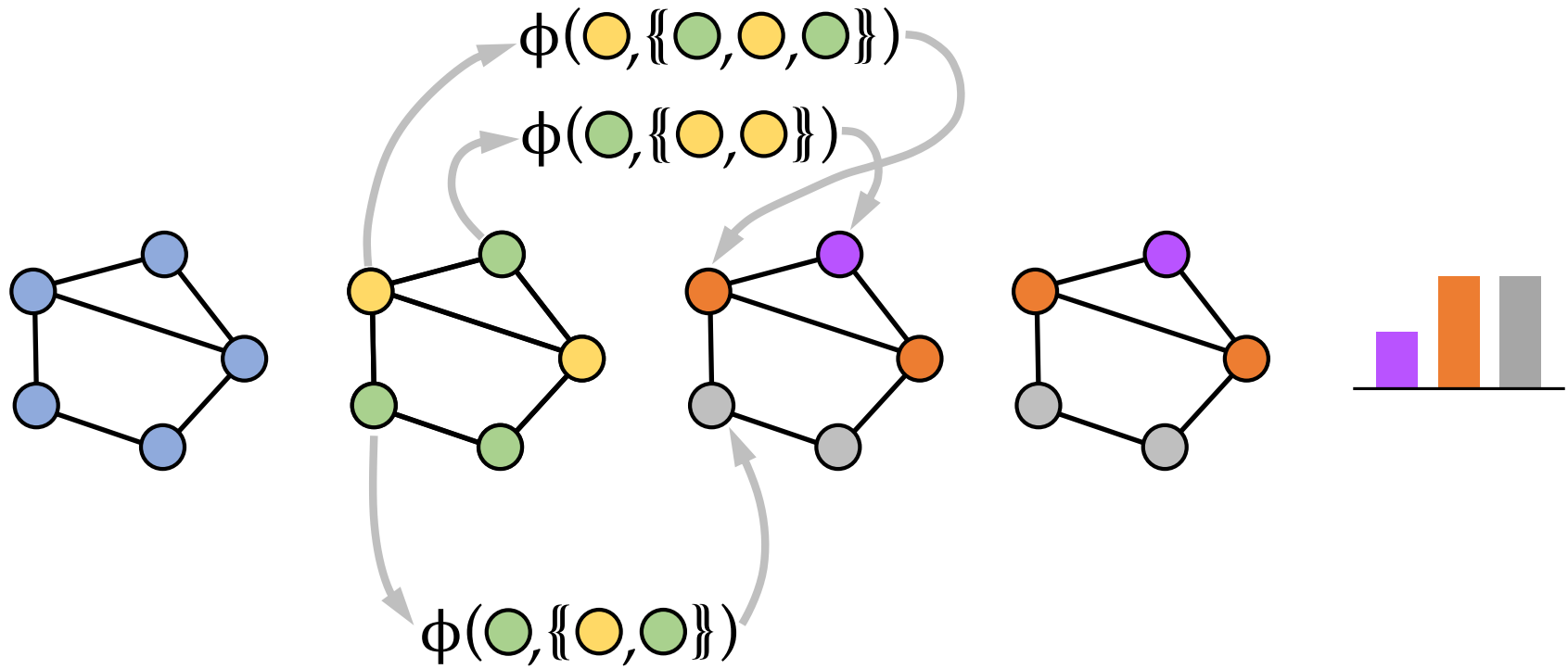
# Weisfeiler-Lehman Test



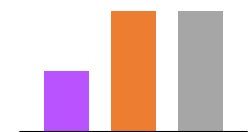
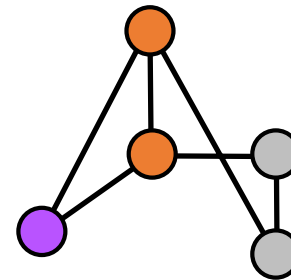
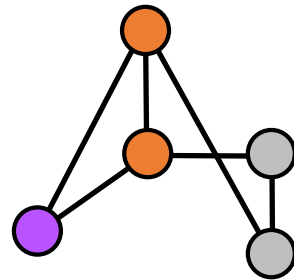
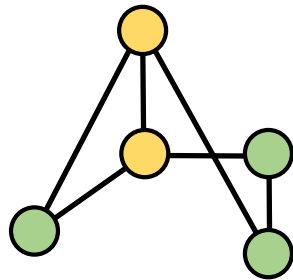
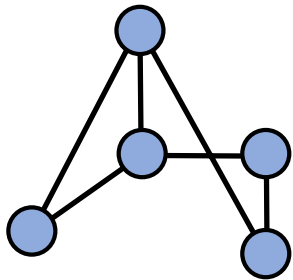
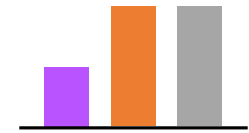
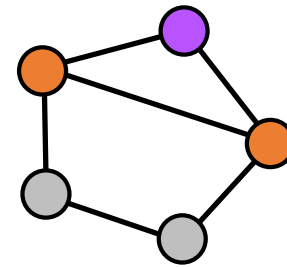
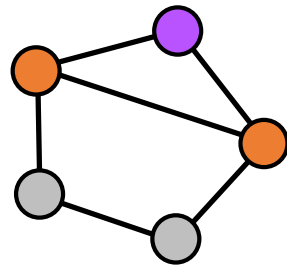
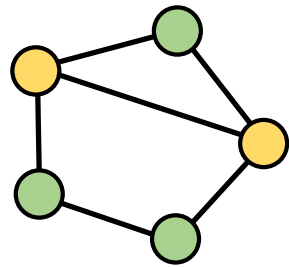
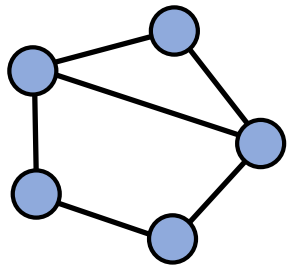
# Weisfeiler-Lehman Test



# Weisfeiler-Lehman Test



# Weisfeiler-Lehman Test

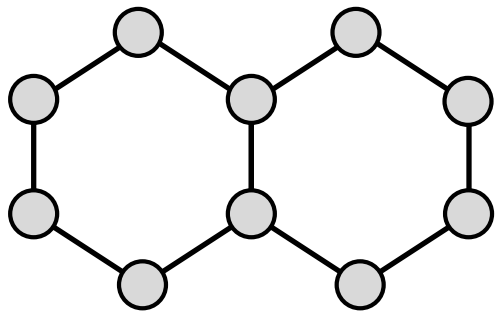




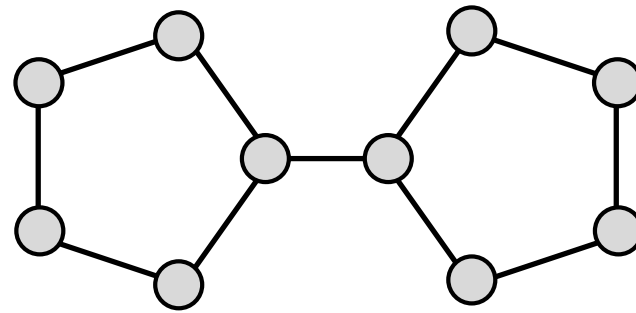
non-isomorphic graphs that are WL-equivalent

**Necessary but insufficient condition!**

*Message-Passing GNNs have limited expressive power!*

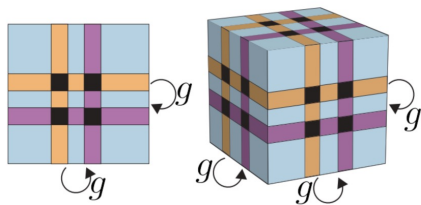


decalin



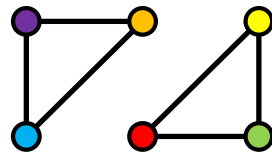
bicyclo[n]pnyl

# Towards More Expressive GNNs



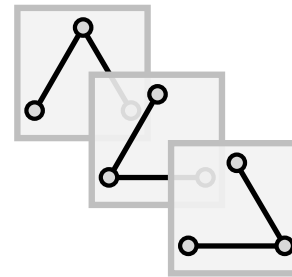
Higher-order  
WL tests

Maron et al. 2019  
Morris et al. 2019



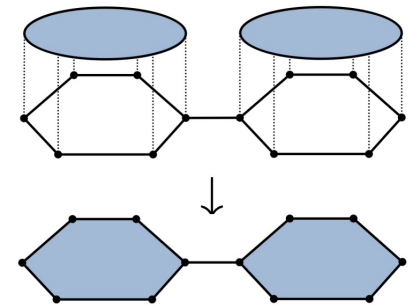
Positional &  
Structural encoding

Monti, Otness et B 2018  
Sato 2020  
Dwivedi et al. 2020  
Bouritsas, Frasca et B 2020  
...many more



Subgraph  
GNNs

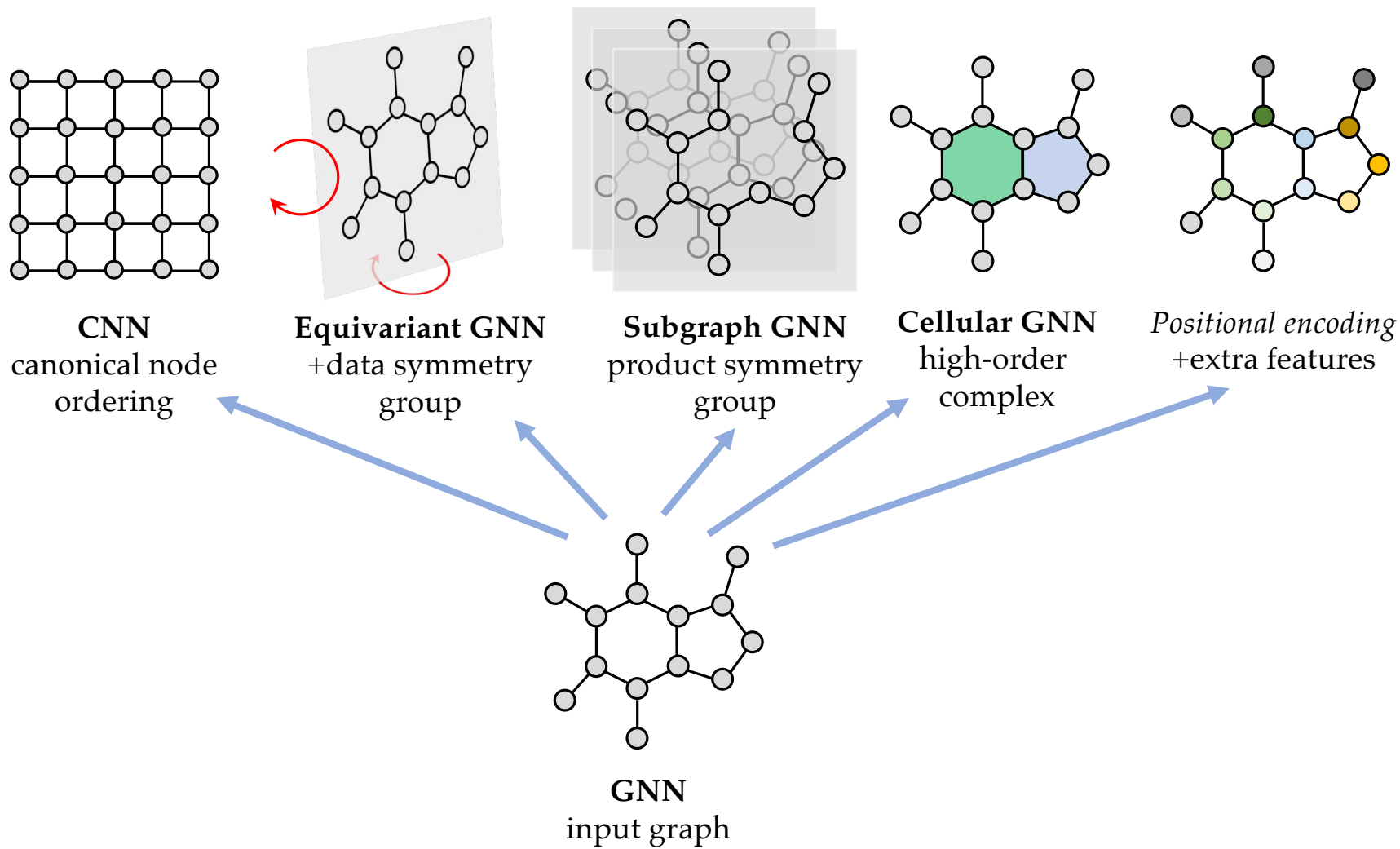
Papp et al. 2021  
Cotta et al. 2021  
Zhao et al. 2021  
Bevilacqua, Frasca et B, Maron 2021  
Frasca et B, Maron 2022



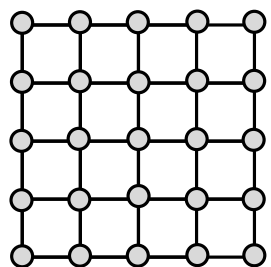
Topological  
message passing

Bodnar, Frasca et B 2021

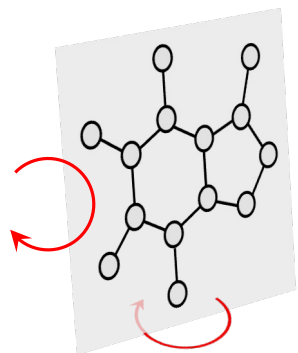




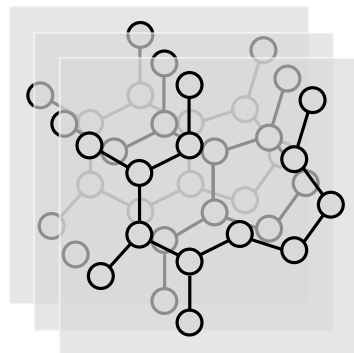
MORE STRUCTURE



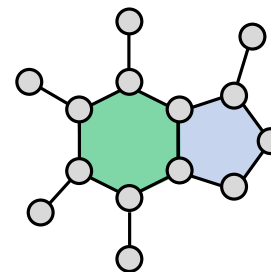
**CNN**  
canonical node  
ordering



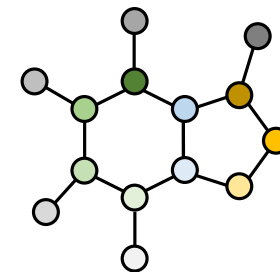
**Equivariant GNN**  
+data symmetry  
group



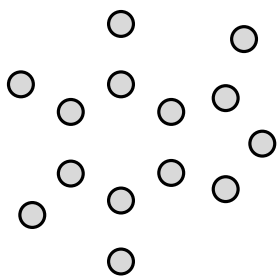
**Subgraph GNN**  
product symmetry  
group



**Cellular GNN**  
high-order  
complex

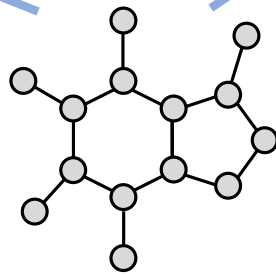


*Positional encoding*  
+extra features



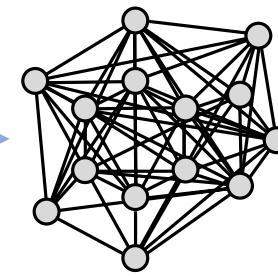
**DeepSet/PointNet**  
no graph

← LESS INTERACTION



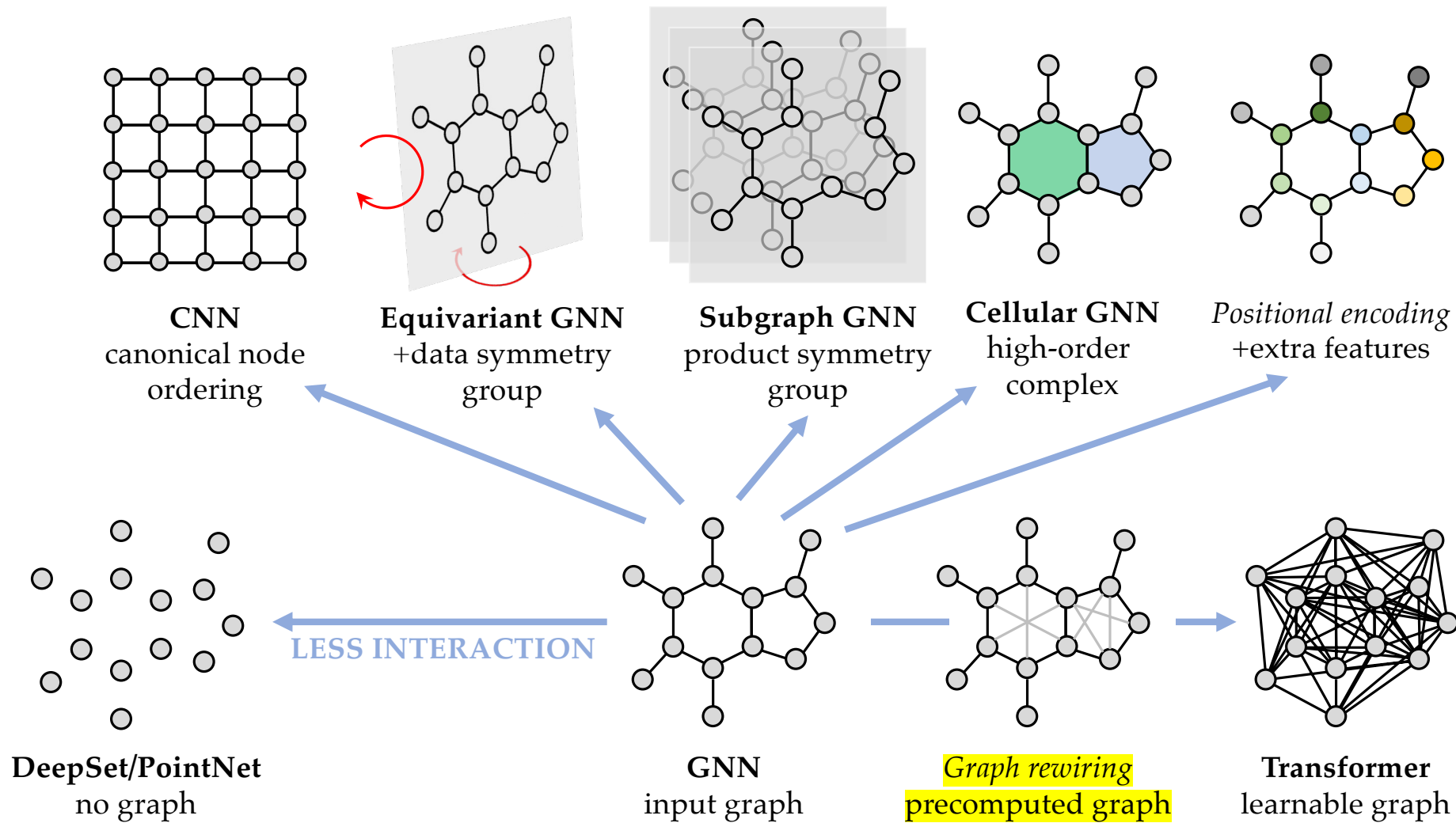
**GNN**  
input graph

→ MORE INTERACTION

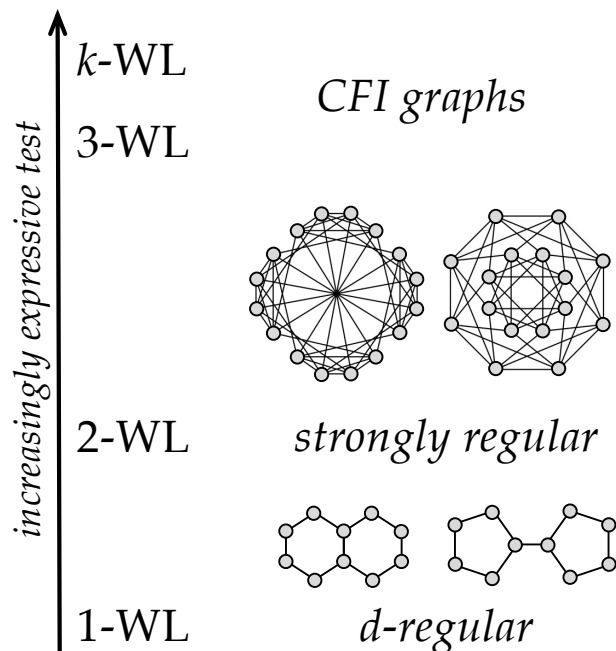


**Transformer**  
learnable graph

MORE STRUCTURE



# Weisfeiler-Lehman hierarchy

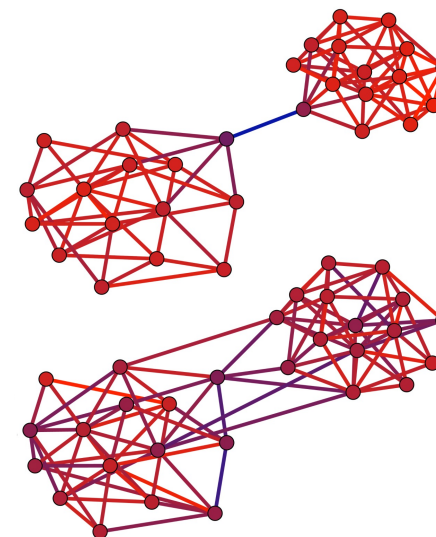


## GNN expressive power

Weisfeiler, Lehman 1968 (2-WL); Babai, Mathon 1979 ( $k$ -WL);  
Cai, Fürer, Immerman 1992 (CFI graphs)

Graphs may be **unfriendly** for message passing resulting in “bottlenecks”

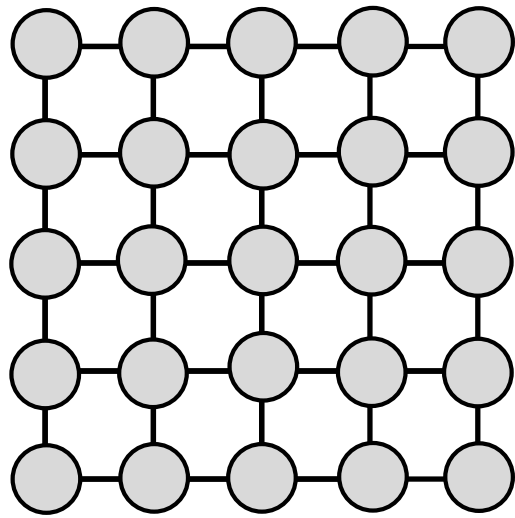
Gap between  
Theory & Practice



## Graph rewiring

Alon, Yahav 2020 (bottlenecks); Hamilton et al. 2017 (neighbour sampling); Klicpera et al. 2019 (diffusion); Topping, Di Giovanni et al. 2022 (Ricci flow); Deac et al. 2022 (expanders)

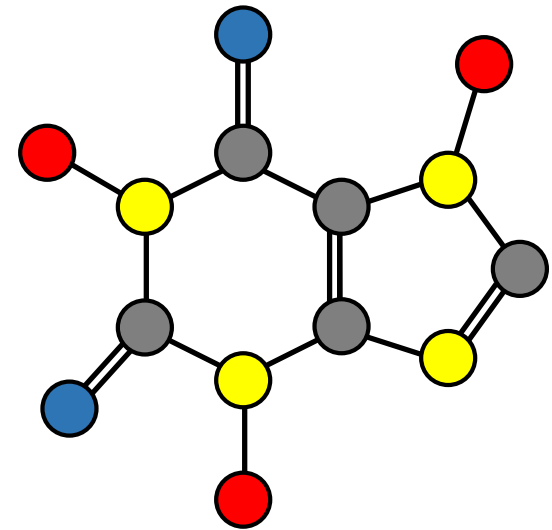
*Graphs vs Meshes vs Grids*



**Grid**

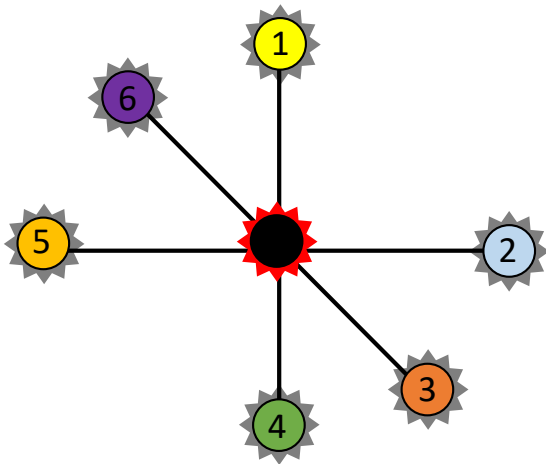


**Mesh**

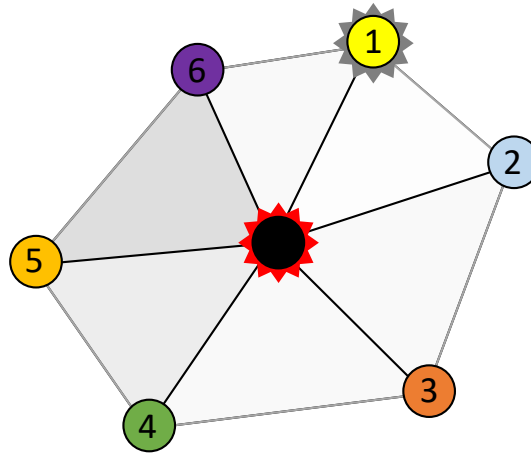


**Graph**

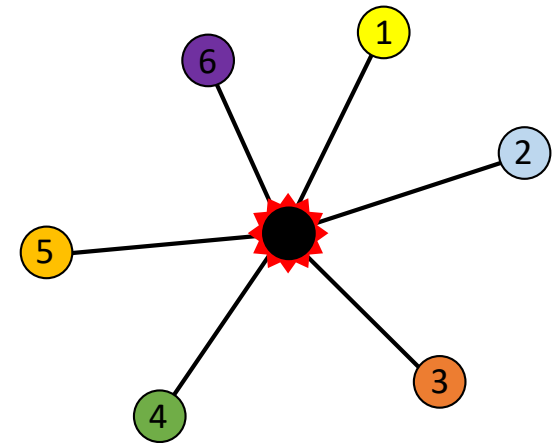
# Graphs vs Meshes vs Grids



**Grid**  
Fixed

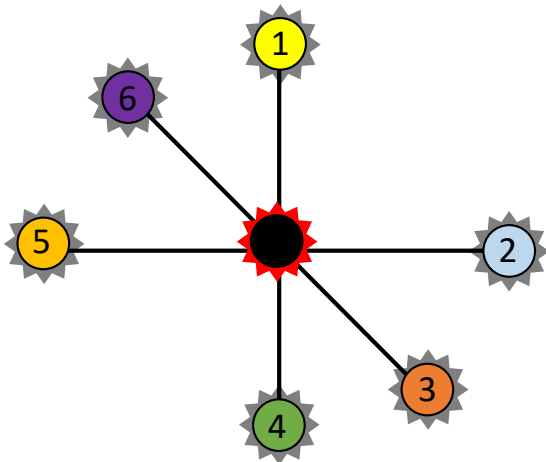


**Mesh**

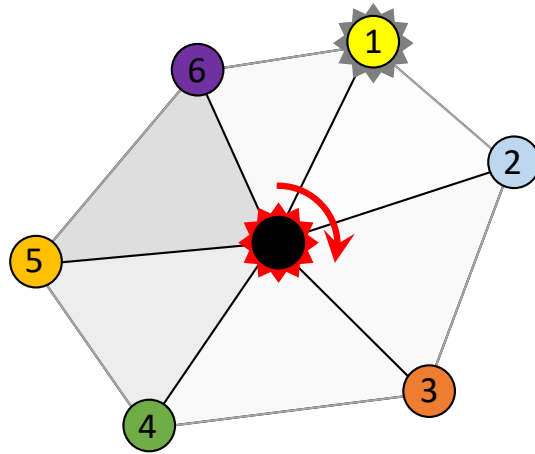


**Graph**

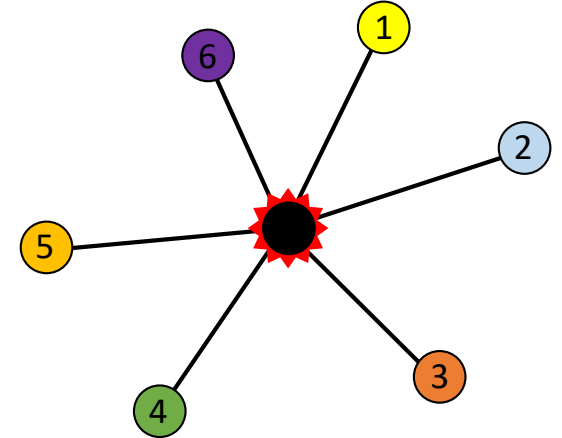
# Graphs vs Meshes vs Grids



**Grid**  
Fixed



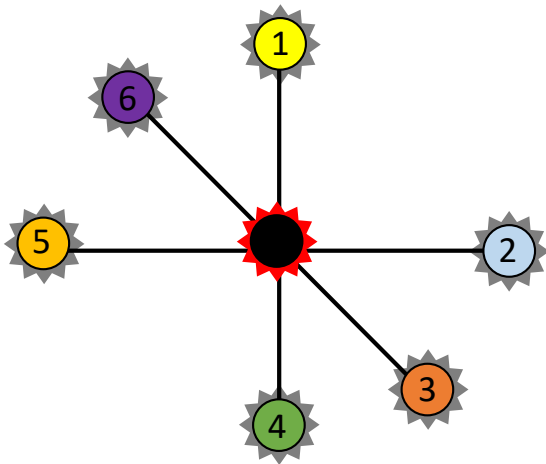
**Mesh**  
Rotation



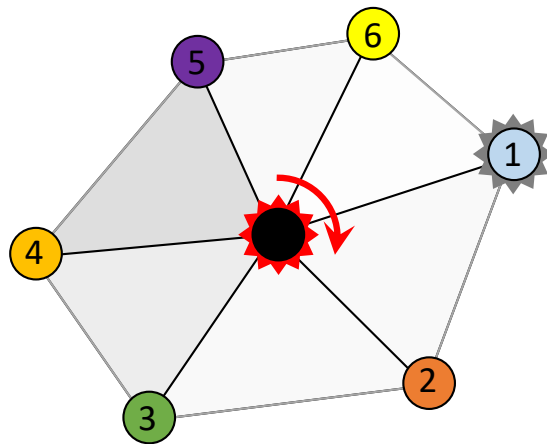
**Graph**



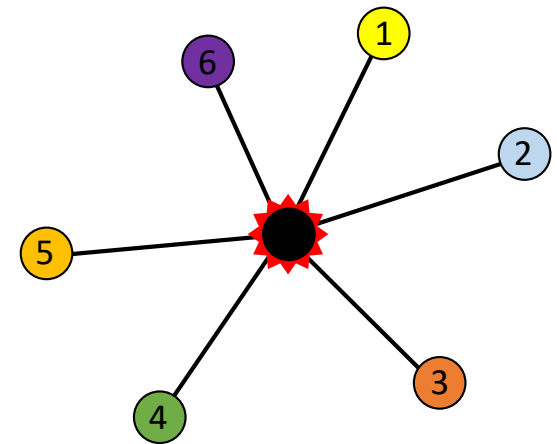
# Graphs vs Meshes vs Grids



**Grid**  
Fixed



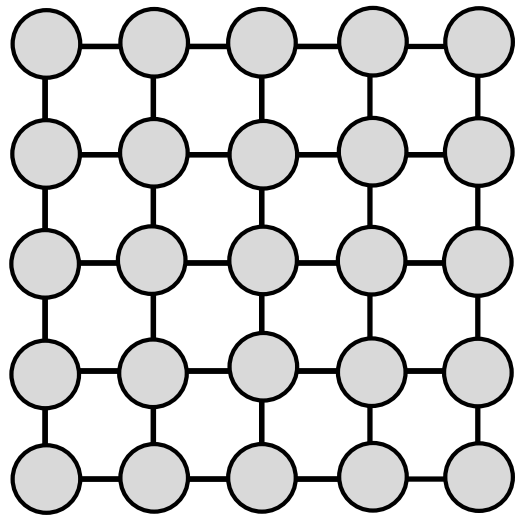
**Mesh**  
Rotation



**Graph**  
Permutation

Graphs have the least structure

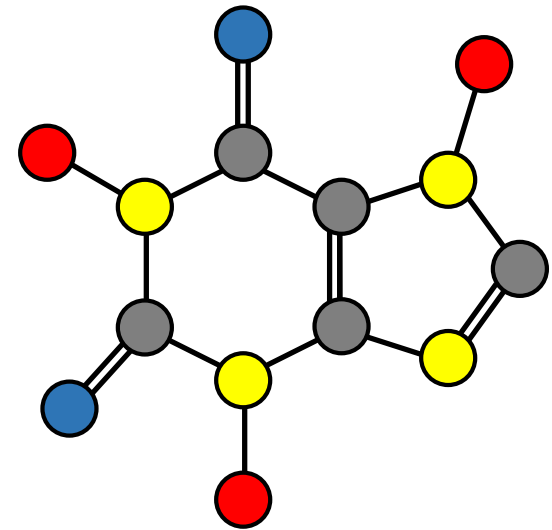
*Graphs vs Meshes vs Grids*



**Grid**

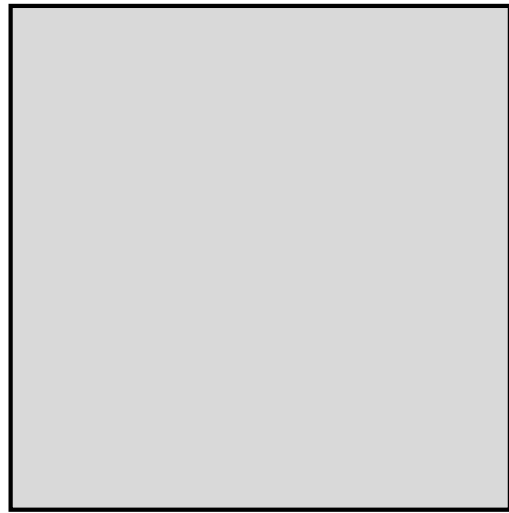


**Mesh**



**Graph**

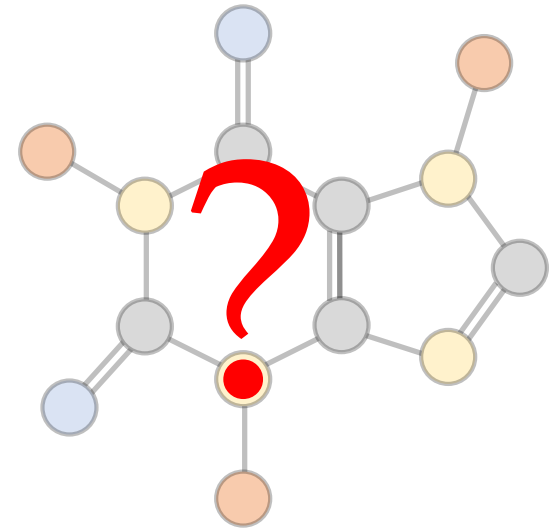
# *Graphs vs Meshes vs Grids*



**Grid**



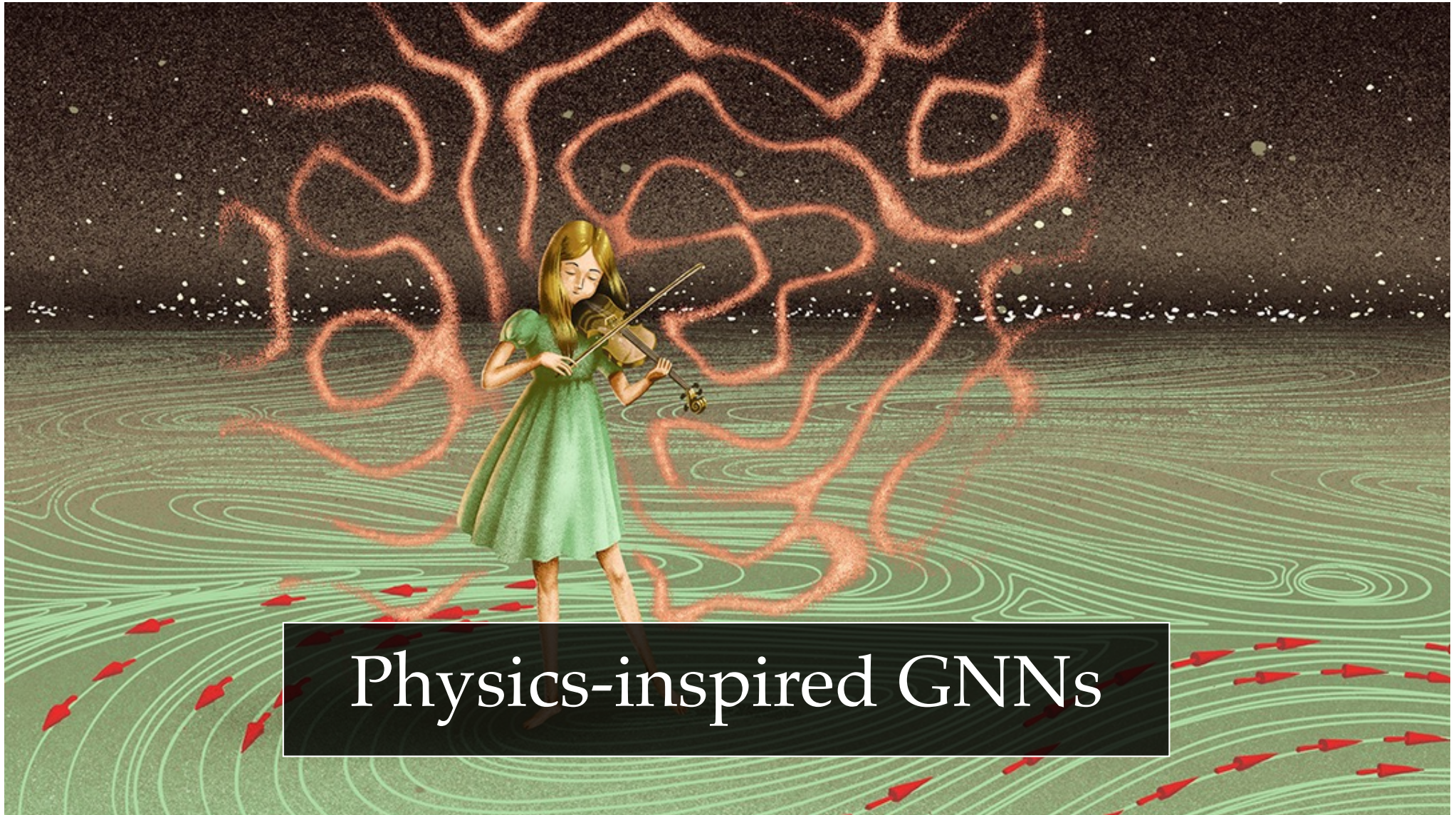
**Mesh**



**Graph**

**Continuous models for GNNs?**

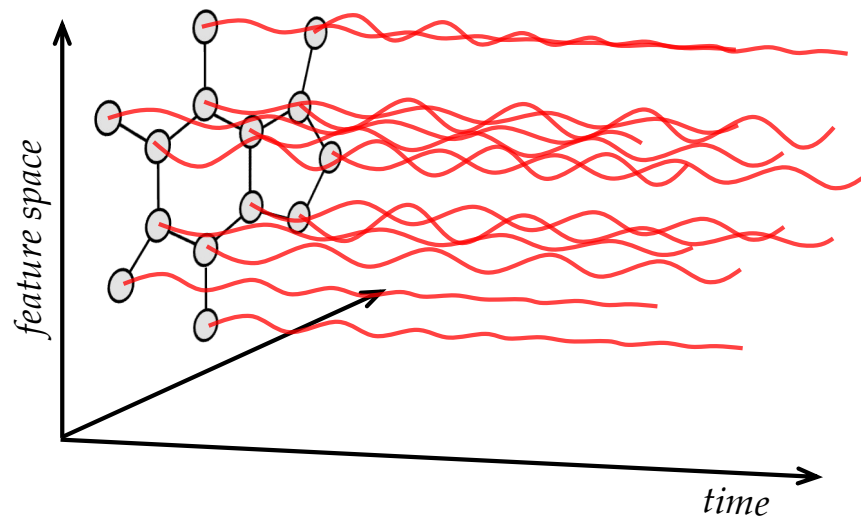




Physics-inspired GNNs

# Physical metaphor of Graph ML

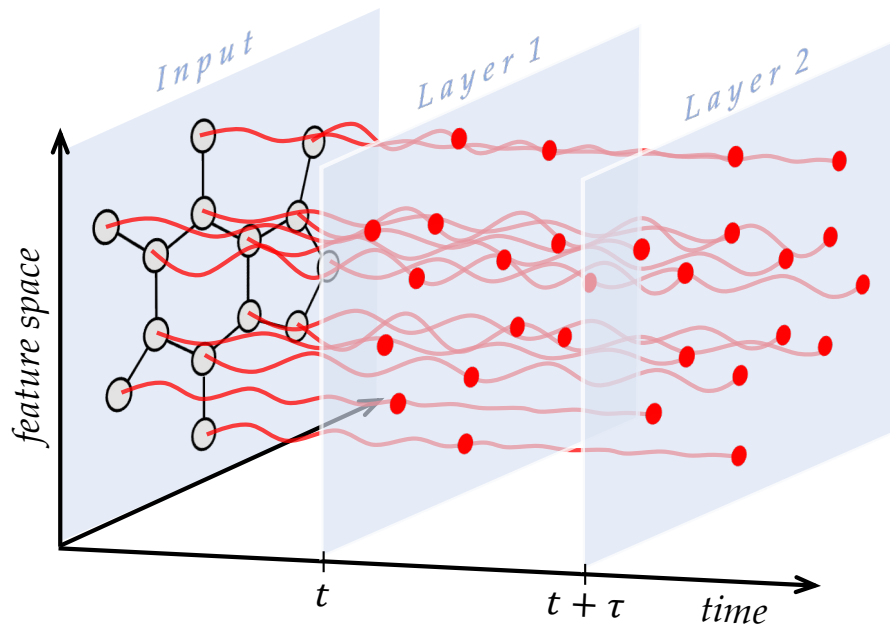
GNN = dynamic system



$$\dot{\mathbf{X}}(t) = \mathbf{F}_{\theta(t)}(\mathbf{X}(t), \mathcal{G})$$

Haber, Ruthotto 2017; Chen et al. 2019 (Neural ODEs); Xhonneau et al. 2020 (CGNN); Chamberlain, Rowbottom, et B. 2021 (GRAND, BLEND)  
Eliasof, Haber 2021 (PDE-GCN); Di Giovanni, Rowbottom et B 2022 (GRAFF), Rusch et B 2022 (GraphCON)

# Physical metaphor of Graph ML



GNN = dynamic system

layers = discretisation of time

graph = coupling function  
(discretisation of space)

$$\mathbf{X}(t + \tau) = \mathbf{X}(t) + \tau \mathbf{F}_{\theta(t)}(\mathbf{X}(t), \mathcal{G})$$



# Heat Diffusion

**Newton Law of Cooling:** “the [temperature] a hot body loses in a given time is proportional to the temperature difference between the object and the environment”

Anonymous 1701

( 824 )

with a little pressing, I took a drop thereof, and in it discover'd a mighty number of living Creatures. I repeated my observation the same evening with the same success, but the next day I could find none of them alive; and whereas I had laid that drop upon a small Copper Plate, I fancied to my self that the exhalation of the moisture might be the cause of their death, and not the cold weather, which at that time was very moderate.

In the beginning of *April* I took the Male seed of a Jack or Pike, but could discover nothing more than in that of a Cod-fish, but having added about four times as much Water in quantity as the matter itself was, and then making my remarks, I could perceive that the *Animalcula* did not only wax stronger and swifter, but, to my great amazement, I saw them move with that celerity, that I could compare it to nothing more than what we have seen with our naked Eye, a River Fish chased by its powerful Enemy, which is just ready to devour it: You must observe that this whole Course was not longer than the Diameter of a single Hair of ones Head.

## VII. *Scala graduum Caloris.*

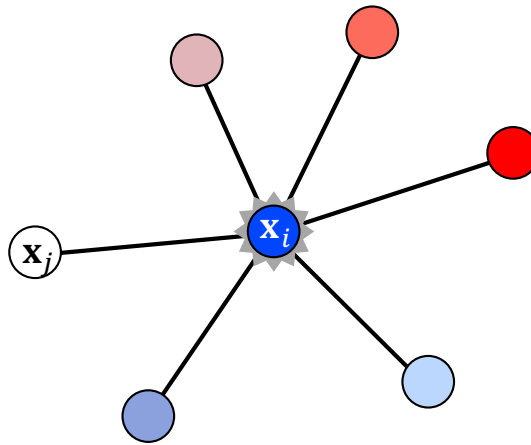
### *Calorum Descriptiones & signa.*

0		C	Alor aeris hybarni ubi aqua incipit gelu rigeferre. Innotescit hic calor accurate locando Thermometrum in nive compressa quo tempore gelu solvitur.	
0,1,2.				Calores aeris hybarni.
2,3,4.				Calores aeris verni & autumnalis.
4,5,6				Calores aeris aestivi.
6				Calor aeris meridiani circa mensem Ju- lium.
12				Calor maximus quem Thermometer ad con- tactum



Isaac Newton

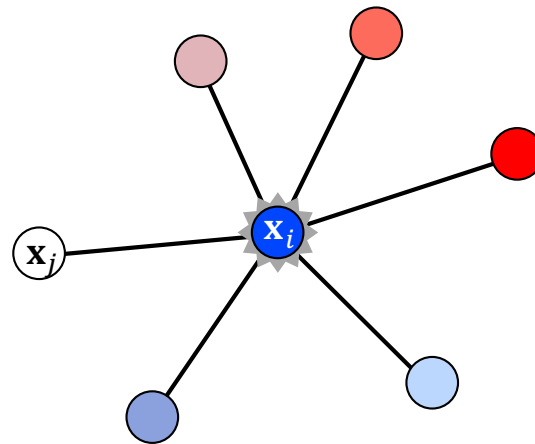
## Heat Diffusion Equation on Graphs



$$\dot{\mathbf{x}}_i(t) = \mathbf{x}_i(t) - \frac{1}{d_i} \sum_{j \in \mathcal{N}_i} a_{ij} \mathbf{x}_j(t)$$



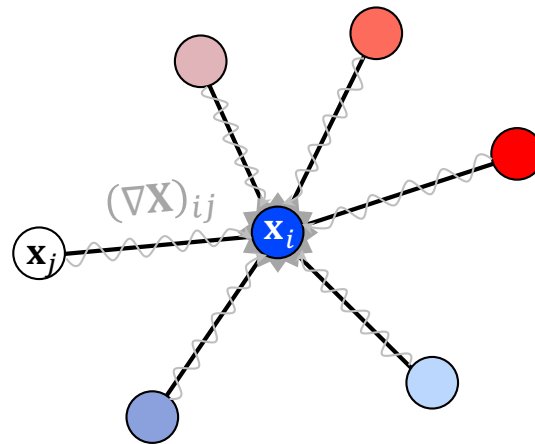
# Heat Diffusion Equation on Graphs



$$\dot{\mathbf{x}}_i(t) = \mathbf{x}_i(t) - \frac{1}{d_i} \sum_{j \in \mathcal{N}_i} a_{ij} \mathbf{x}_j(t)$$

rate of temperature change      self temperature      temperature of the environment

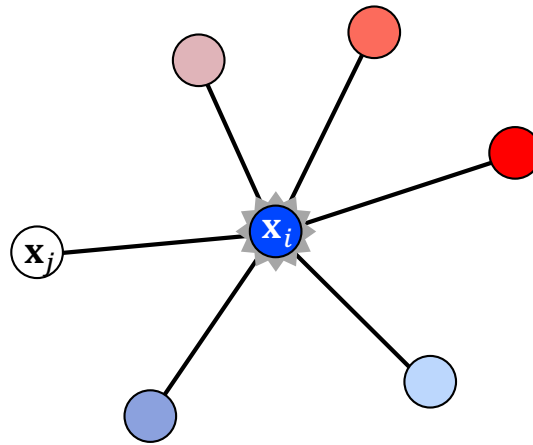
# Heat Diffusion Equation on Graphs



$$\dot{\mathbf{x}}_i(t) = \frac{1}{d_i} \sum_{j \in \mathcal{N}_i} a_{ij} \underbrace{(\mathbf{x}_i(t) - \mathbf{x}_j(t))}_{\text{gradient } -(\nabla X)_{ij}}$$

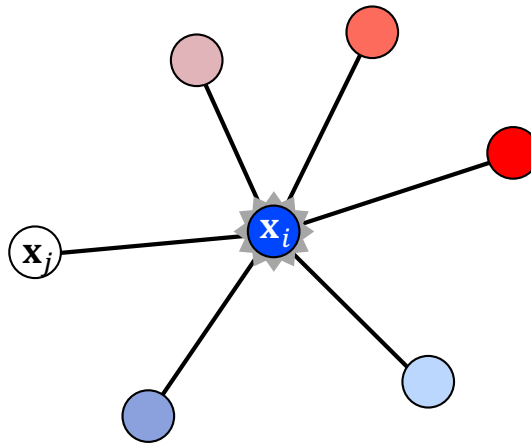
divergence  
div

## *Heat Diffusion Equation on Graphs*



$$\dot{\mathbf{X}}(t) = -\text{div}(\nabla \mathbf{X}(t))$$

## *Heat Diffusion Equation on Graphs*

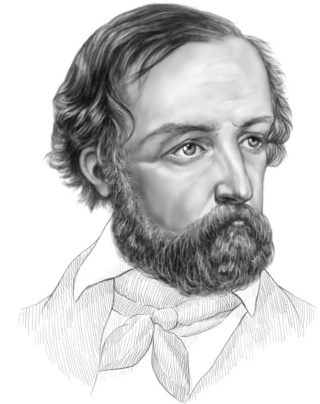


$$\dot{\mathbf{X}}(t) = \Delta \mathbf{X}(t)$$

## Heat Equation as a prototypical Gradient Flow

$$\dot{\mathbf{X}}(t) = -\nabla \mathcal{E}(\mathbf{X}(t))$$

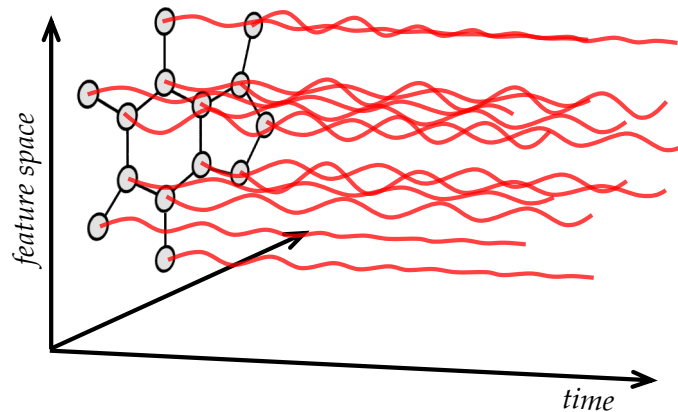
$$\mathcal{E}_{\text{DIR}}(\mathbf{X}) = \frac{1}{2} \sum_{j \in \mathcal{N}_i} \|(\nabla \mathbf{X})_{ij}\|^2 = \frac{1}{2} \text{trace}(\mathbf{X}^T \Delta \mathbf{X})$$



**G. Dirichlet**

- Heat diffusion equation is the gradient flow of the Dirichlet energy
- “Smoothness” of the node features
- Dirichlet energy **decreases along the flow**
- In the limit  $t \rightarrow \infty$  results in “oversmoothing”
- Not very expressive: works only in homophilic graphs (“similar neighbours”)

# Gradient Flow Framework (GRAFF)



**Traditional GNNs**

$$\dot{\mathbf{X}}(t) = \mathbf{F}_{\theta(t)}(\mathbf{X}(t), \mathcal{G})$$

- Parametrize **evolution equations**

**GRAFF**

$$\dot{\mathbf{X}}(t) = -\nabla \mathcal{E}_{\theta(t)}(\mathbf{X}(t), \mathcal{G})$$

- Parametrize **energy**
- Derive evolution equation as GF
- Better interpretability

## *Generalised parametric Dirichlet energy*

$$\varepsilon_{\theta}(\mathbf{X}) = \frac{1}{2} \sum_{i=1}^n \langle \mathbf{x}_i, \mathbf{\Omega} \mathbf{x}_i \rangle - \frac{1}{2} \sum_{j \in \mathcal{N}_i} \bar{a}_{ij} \langle \mathbf{x}_i, \mathbf{W} \mathbf{x}_j \rangle$$

- Energy of a system of particles (nodes) parameterised by  $d \times d$  matrices  $\mathbf{\Omega}$  and  $\mathbf{W}$

## Generalised parametric Dirichlet energy

$$\varepsilon_{\theta}(\mathbf{X}) = \frac{1}{2} \sum_{i=1}^n \langle \mathbf{x}_i, \mathbf{\Omega} \mathbf{x}_i \rangle - \frac{1}{2} \sum_{j \in \mathcal{N}_i} \bar{a}_{ij} \langle \mathbf{x}_i, \mathbf{W} \mathbf{x}_j \rangle$$

external energy

- Energy of a system of particles (nodes) parameterised by  $d \times d$  matrices  $\mathbf{\Omega}$  and  $\mathbf{W}$
- **External energy** term acting on all particles

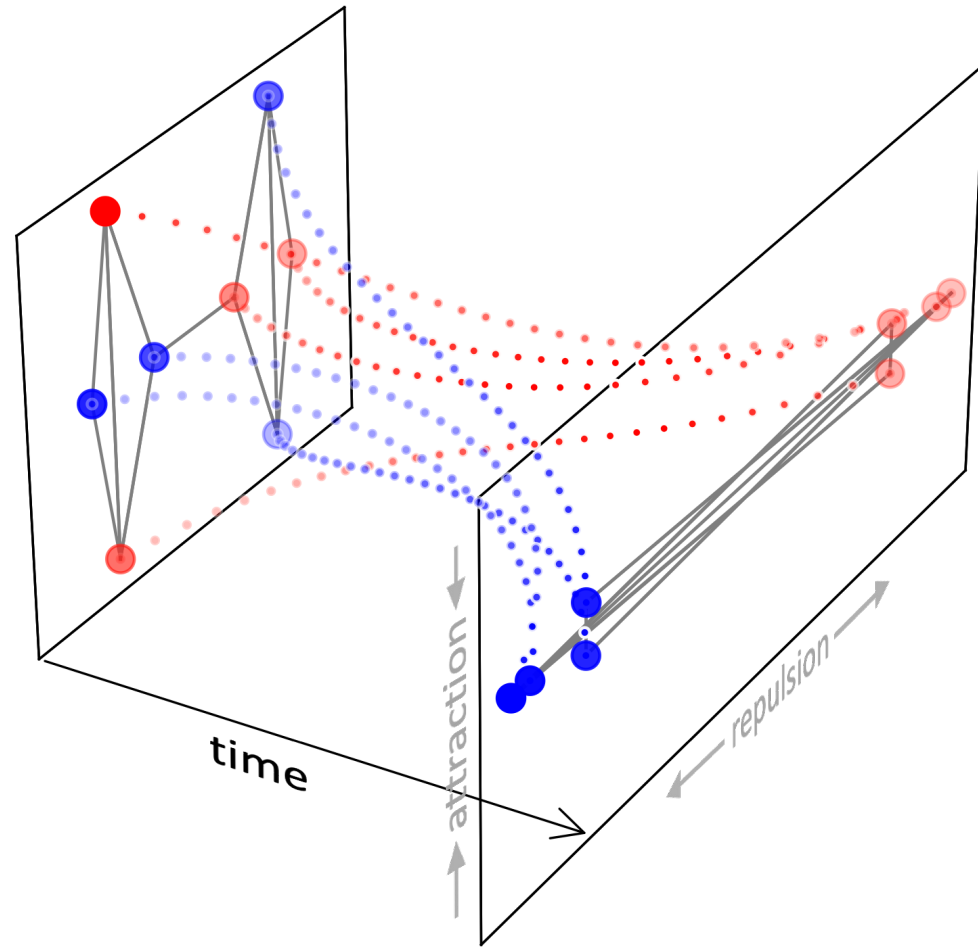


## Generalised parametric Dirichlet energy

$$\varepsilon_{\theta}(\mathbf{X}) = \frac{1}{2} \sum_{i=1}^n \langle \mathbf{x}_i, \mathbf{\Omega} \mathbf{x}_i \rangle - \frac{1}{2} \sum_{j \in \mathcal{N}_i} \bar{a}_{ij} \langle \mathbf{x}_i, \mathbf{W} \mathbf{x}_j \rangle$$

external energy internal energy  
(pair-wise interactions)

- Energy of a system of particles (nodes) parameterised by  $d \times d$  matrices  $\mathbf{\Omega}$  and  $\mathbf{W}$
- **External energy** term acting on all particles
- **Internal energy** term: interactions between nodes along edges of the graph
  - **Attractive** interactions along positive eigenvectors of  $\mathbf{W}$
  - **Repulsive** interactions along negative eigenvectors of  $\mathbf{W}$



## *Gradient Flow of $\mathcal{E}_\theta$*

$$\dot{\mathbf{X}}(t) = -\nabla \mathcal{E}_\theta(\mathbf{X}(t)) = -\mathbf{X}(t) \frac{\mathbf{\Omega} + \mathbf{\Omega}^T}{2} + \bar{\mathbf{A}} \mathbf{X}(t) \frac{\mathbf{W} + \mathbf{W}^T}{2}$$

## Gradient Flow of $\mathcal{E}_\theta$

$$\dot{\mathbf{X}}(t) = -\nabla \mathcal{E}_\theta(\mathbf{X}(t)) = -\mathbf{X}(t) \frac{\mathbf{\Omega} + \mathbf{\Omega}^T}{2} + \bar{\mathbf{A}}\mathbf{X}(t) \frac{\mathbf{W} + \mathbf{W}^T}{2}$$

*matrices appear only in symmetrized form*

## *Gradient Flow of $\mathcal{E}_\theta$*

$$\dot{\mathbf{X}}(t) = -\mathbf{X}(t)\mathbf{\Omega} + \bar{\mathbf{A}}\mathbf{X}(t)\mathbf{W}$$

- Symmetric matrices  $\mathbf{\Omega}$  and  $\mathbf{W}$
- Time-independent parameters:  $\mathbf{\Omega}(t) = \mathbf{\Omega}$ ,  $\mathbf{W}(t) = \mathbf{W}$

## *Discretised Gradient Flow of $\mathcal{E}_\theta$*

$$\mathbf{X}(t + \tau) = \mathbf{X}(t) + \tau(-\mathbf{X}(t)\mathbf{\Omega} + \bar{\mathbf{A}}\mathbf{X}(t)\mathbf{W})$$

- Residual convolutional-type GNN
- Symmetric weights
- Symmetry constraint does not diminish expressive power
- Shared weights across layers

## GRAFF

$$\mathbf{X}(t + \tau) = \mathbf{X}(t) + \tau \bar{\mathbf{A}} \mathbf{X}(t) \mathbf{W}$$

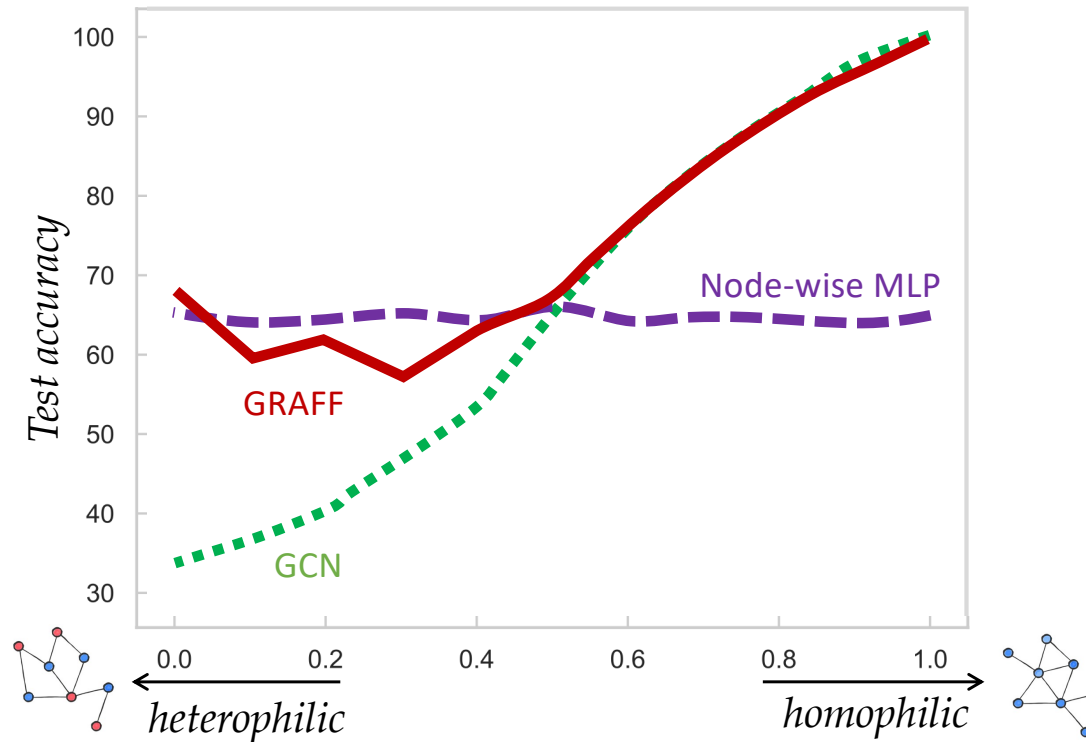
- Residual
- Symmetric weights
- Shared weights
- No nonlinear activation
- Gradient flow (interpretability)
- $d^2/2$  weights
- Can induce both low- and high-frequency dominated dynamics
- Works with heterophilic graphs

## GCN

$$\mathbf{X}(t + \tau) = \tau \sigma(\bar{\mathbf{A}} \mathbf{X}(t) \mathbf{W}(t))$$

- Non-residual
- Non-symmetric weights
- Different weights per layer
- Nonlinear activation
- Not a gradient flow
- $Ld^2$  weights
- Only low-frequency dominated dynamics (oversmoothing)
- Only homophilic graphs

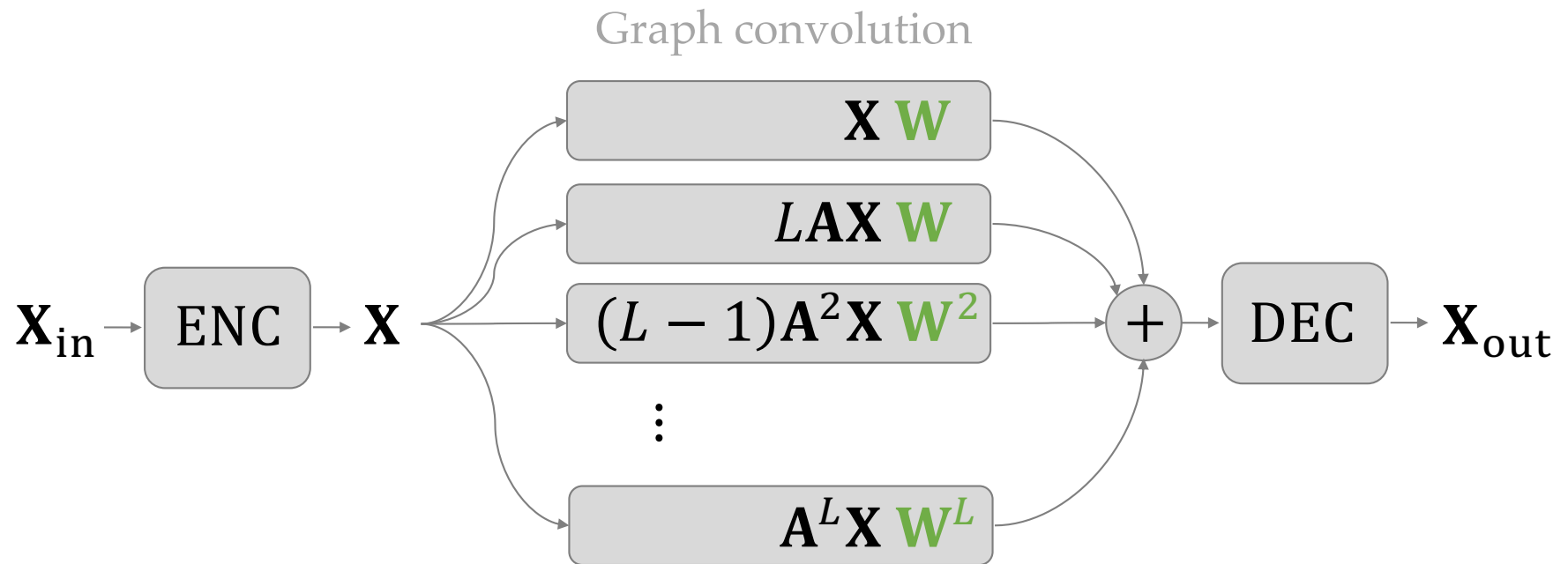
# Homophily vs Heterophily



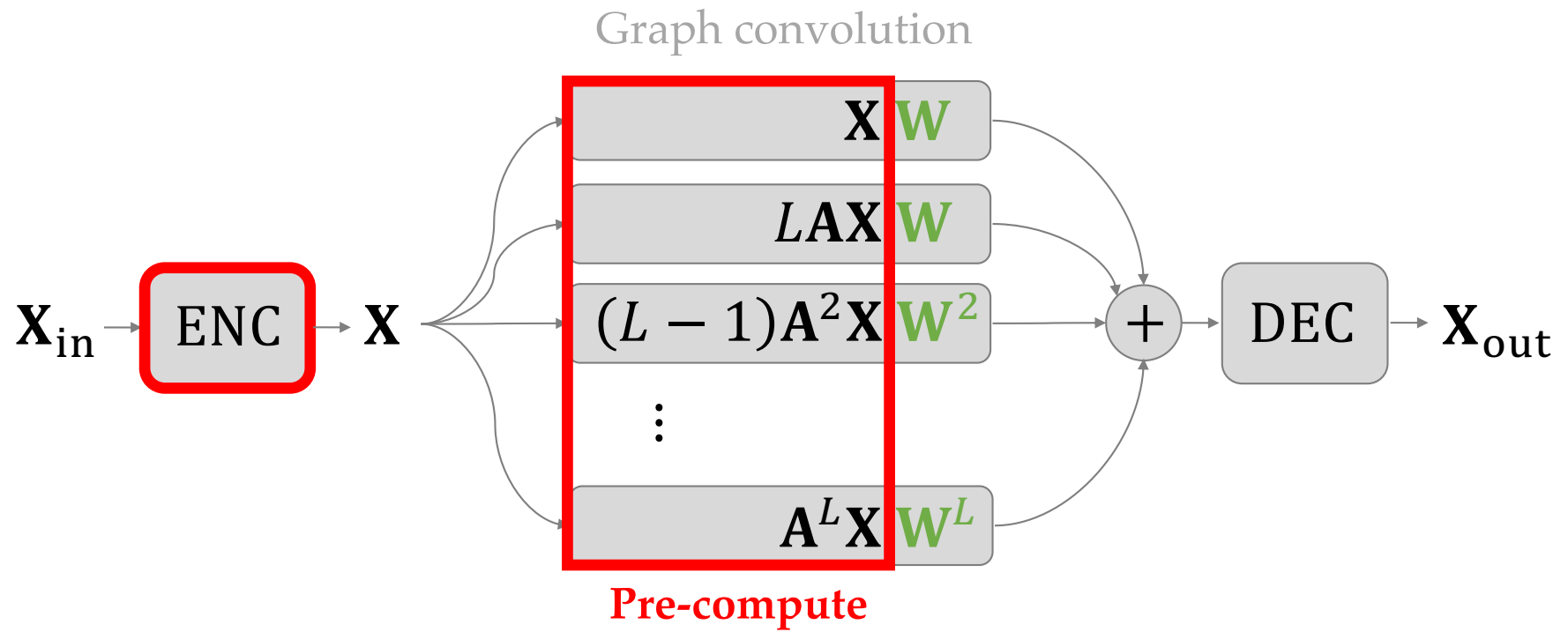
Synthetic Cora node classification task



# Scalability



# Scalability



## *Spectral analysis of GRAFF*

- $\mathbf{\Delta} = \mathbf{\Phi}\mathbf{\Lambda}\mathbf{\Phi}^T$  orthogonal eigendecomposition of the graph Laplacian
- $\mathbf{W} = \mathbf{\Psi}\mathbf{M}\mathbf{\Psi}^T$  orthogonal eigendecomposition of channel mixing weights
- Output of  $L$  layers GRAFF

$$\mathbf{X}(L\tau) = \sum_{k=1}^d \sum_{l=0}^{n-1} (1 + \tau\mu_k(1 - \lambda_l))^L \langle \mathbf{X}(0), \boldsymbol{\psi}_l \otimes \boldsymbol{\phi}_l \rangle \boldsymbol{\psi}_l \otimes \boldsymbol{\phi}_l$$

- **Low frequencies** ( $\lambda_l < 1$ ) magnified by **positive** eigenvalues of  $\mathbf{W}$  ( $\mu_k > 0$ )
- **High frequencies** ( $\lambda_l > 1$ ) magnified by **negative** eigenvalues of  $\mathbf{W}$  ( $\mu_k < 0$ )

## *Spectral analysis of GRAFF*

- $\Delta = \Phi \Lambda \Phi^T$  orthogonal eigendecomposition of the graph Laplacian
- $\mathbf{W} = \Psi \mathbf{M} \Psi^T$  orthogonal eigendecomposition of channel mixing weights
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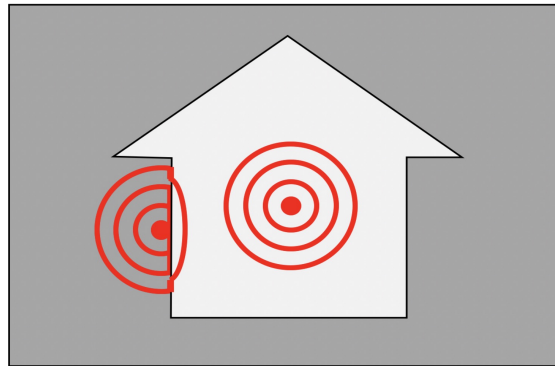
If eigenvalues of  $\mathbf{W}$  are sufficiently negative, then GRAFF dynamics is **high-frequency dominant**:  $\mathcal{E}_{\text{DIR}}(\mathbf{X}(t)/\|\mathbf{X}(t)\|) \rightarrow \lambda_{\text{max}}/2$

**No oversmoothing!**

# Non-homogeneous Diffusion in Image Processing

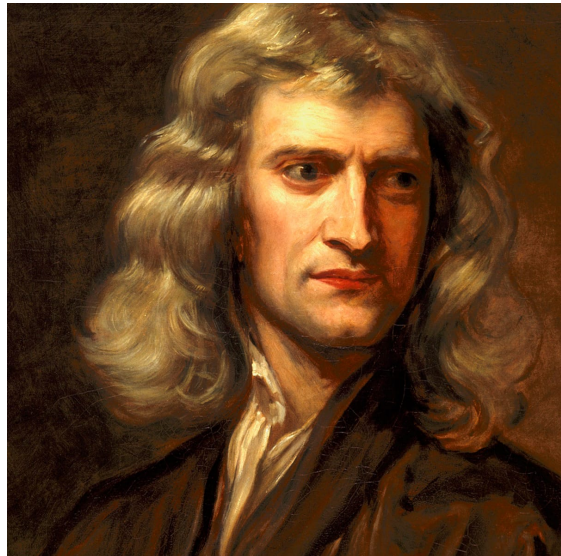
$$\dot{\mathbf{X}}(t) = -\text{div} \left( \frac{\nabla \mathbf{X}(t)}{1 + c \|\nabla \mathbf{X}(t)\|^2} \right)$$

*edge indicator*



“Do not diffuse across edges”

# *Non-homogeneous Diffusion in Image Processing*

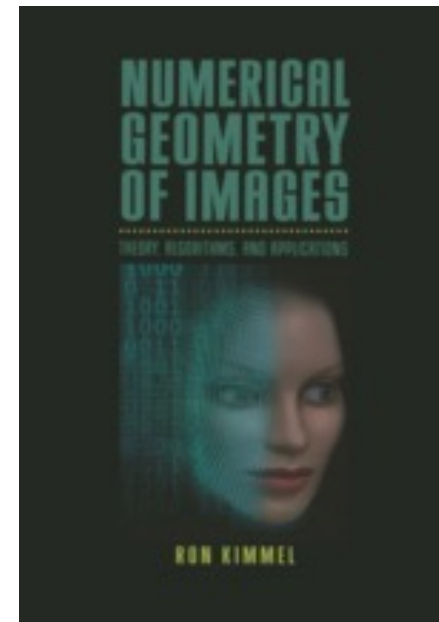
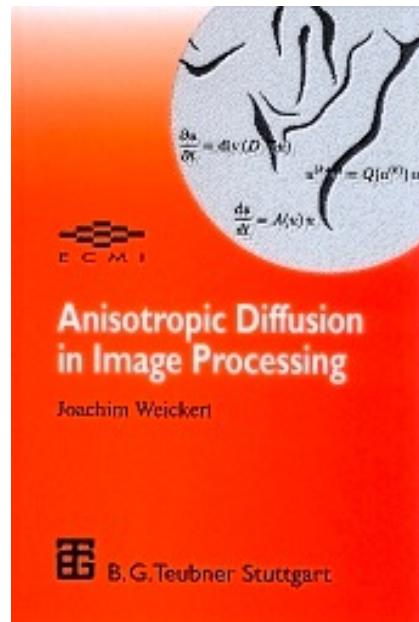
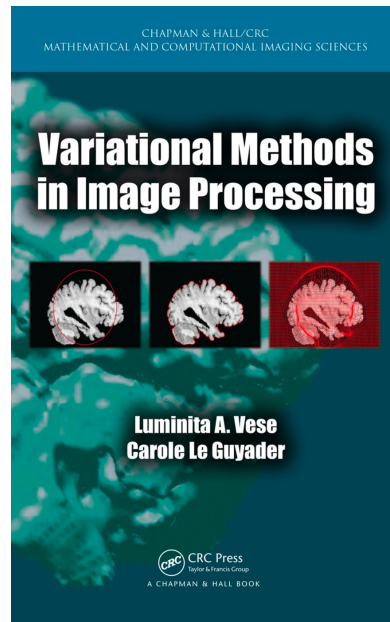


Homogeneous  
diffusion



Non-homogeneous  
diffusion

# Diffusion in Image Processing



Perona, Malik 1990; Kimmel et al. 1997; Sochen et al. 1998; Tomasi, Manduchi 1998; Weickert 1998; Buades et al. 2005

## *Non-homogeneous Diffusion Equation on Graphs*

$$\dot{\mathbf{x}}_i(t) = \sum_{j \in \mathcal{N}_i} a(\mathbf{x}_i(t), \mathbf{x}_j(t)) (\mathbf{x}_j(t) - \mathbf{x}_i(t))$$

*Explicit (Forward Euler) discretization with timestep  $\tau$ :*

$$\mathbf{x}_i(t + \tau) = \mathbf{x}_i(t) + \tau \sum_{j \in \mathcal{N}_i} a(\mathbf{x}_i(t), \mathbf{x}_j(t)) (\mathbf{x}_j(t) - \mathbf{x}_i(t))$$



## Non-homogeneous Diffusion Equation on Graphs

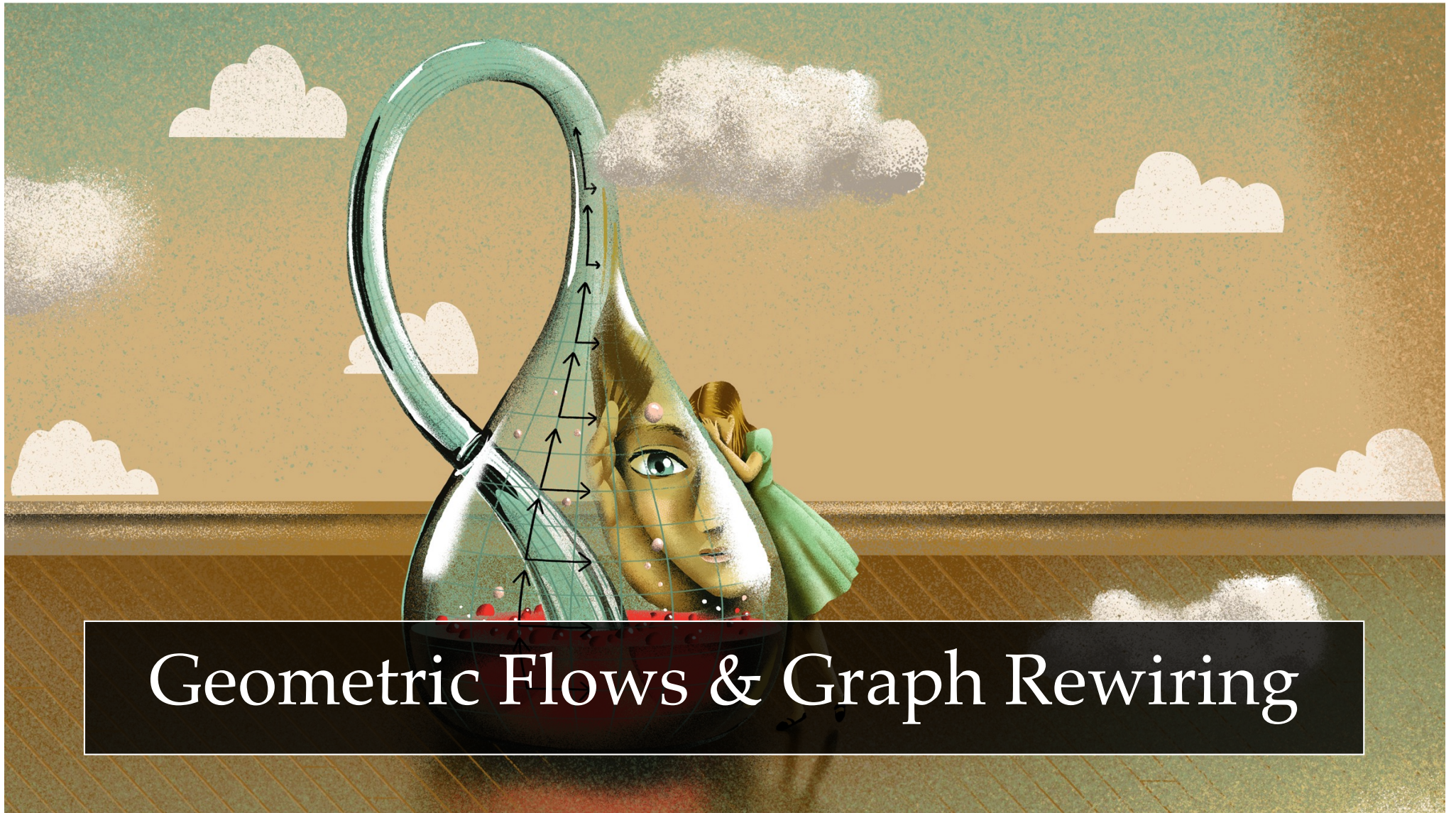
$$\dot{\mathbf{x}}_i(t) = \sum_{j \in \mathcal{N}_i} a(\mathbf{x}_i(t), \mathbf{x}_j(t)) (\mathbf{x}_j(t) - \mathbf{x}_i(t))$$

Explicit (Forward Euler) discretization with timestep  $\tau$ :

$$\mathbf{x}_i(t + \tau) = \sum_{j \in \mathcal{N}_i} a(\mathbf{x}_i(t), \mathbf{x}_j(t)) \mathbf{x}_j(t)$$

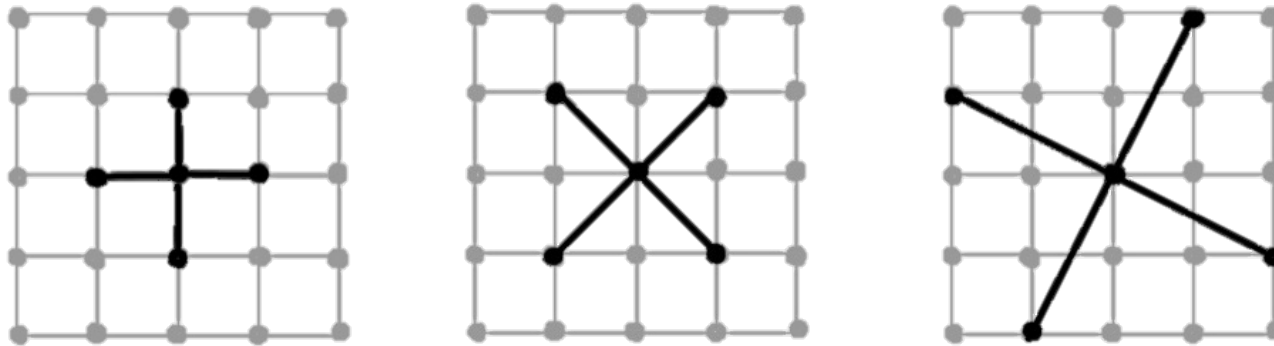
normalised  $\sum_j a_{ij} = 1$   
unit step  $\tau = 1$

**GAT is a particular discretisation of graph diffusion**



# Geometric Flows & Graph Rewiring

*Spatial Derivative: Graph Rewiring?*



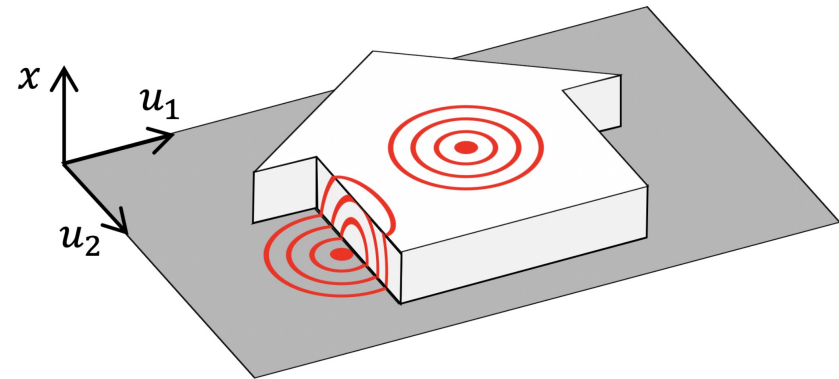
Different discretisations of 2D Laplacian

## *Images as embedded manifolds*



$$\dot{\mathbf{X}} = -\text{div}(a(\mathbf{X})\nabla\mathbf{X})$$

Non-linear diffusion



$$\dot{\mathbf{Z}} = \Delta_{\mathbf{G}}\mathbf{Z}$$

Non-Euclidean diffusion



# Beltrami flow

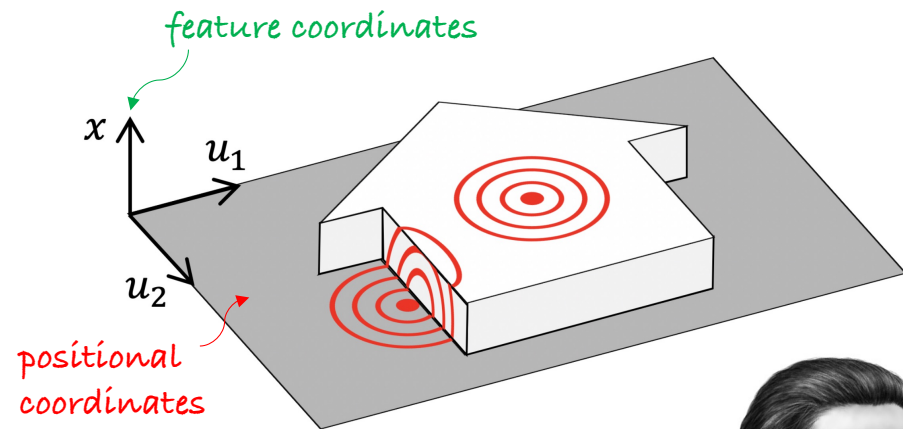
- Consider image as embedded 2-manifold

$$\mathbf{Z}(\mathbf{u}) = (\mathbf{u}, \alpha \mathbf{X}(\mathbf{u}))$$

- Pullback metric:  $2 \times 2$  matrix

$$\mathbf{G} = \mathbf{I} + \alpha^2 (\nabla_{\mathbf{u}} \mathbf{X}(\mathbf{u}))^T \nabla_{\mathbf{u}} \mathbf{X}(\mathbf{u})$$

- Beltrami flow = gradient flow of the Polyakov energy (harmonic energy of the embedding used in string theory)



$$\dot{\mathbf{Z}} = \Delta_{\mathbf{G}} \mathbf{Z}$$

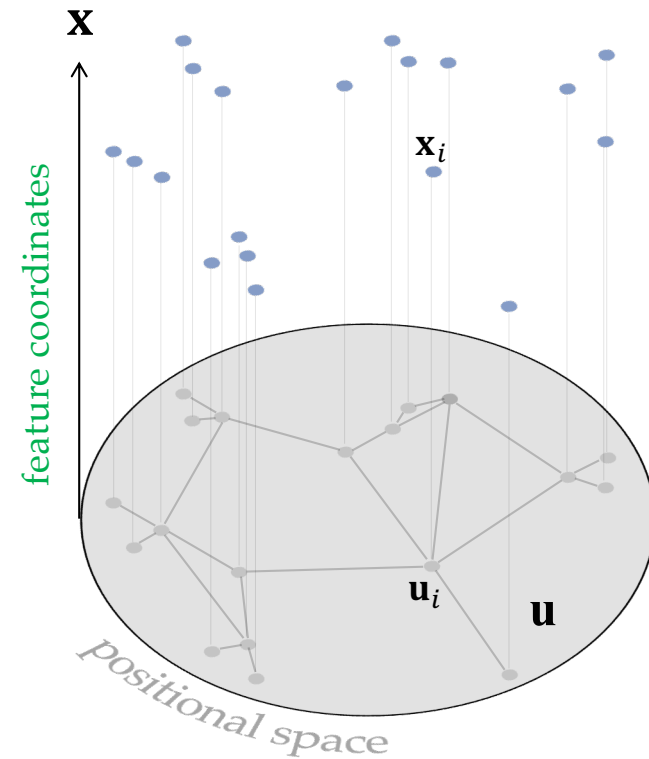


Eugenio Beltrami

## Graph Beltrami flow

- Graph with positional and feature node coordinates  $\mathbf{z}_i = (\mathbf{u}_i, \mathbf{x}_i)$
- **Graph Beltrami flow**

$$\dot{\mathbf{z}}_i(t) = \sum_{j \in \mathcal{N}_i} a(\mathbf{z}_i(t), \mathbf{z}_j(t)) (\mathbf{z}_j(t) - \mathbf{z}_i(t))$$

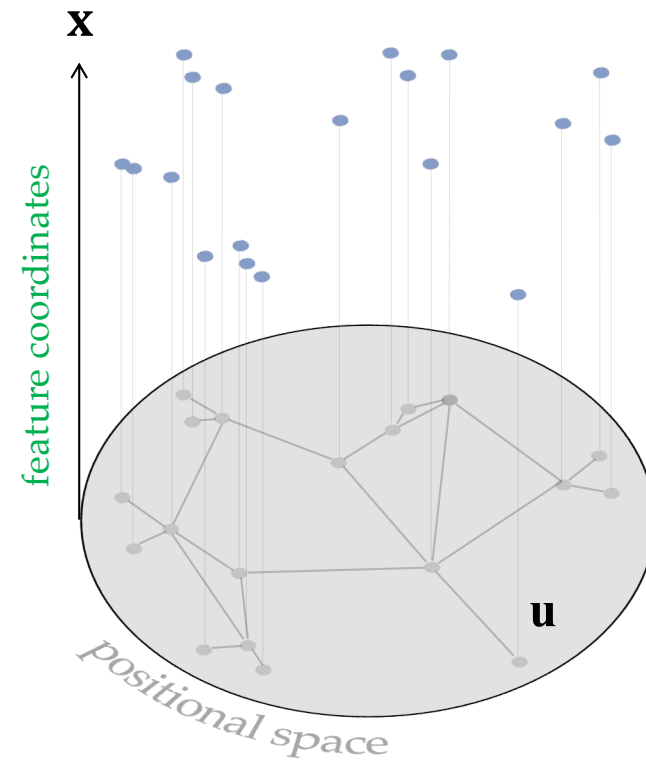


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- Evolution of  $\mathbf{x}$  = feature diffusion

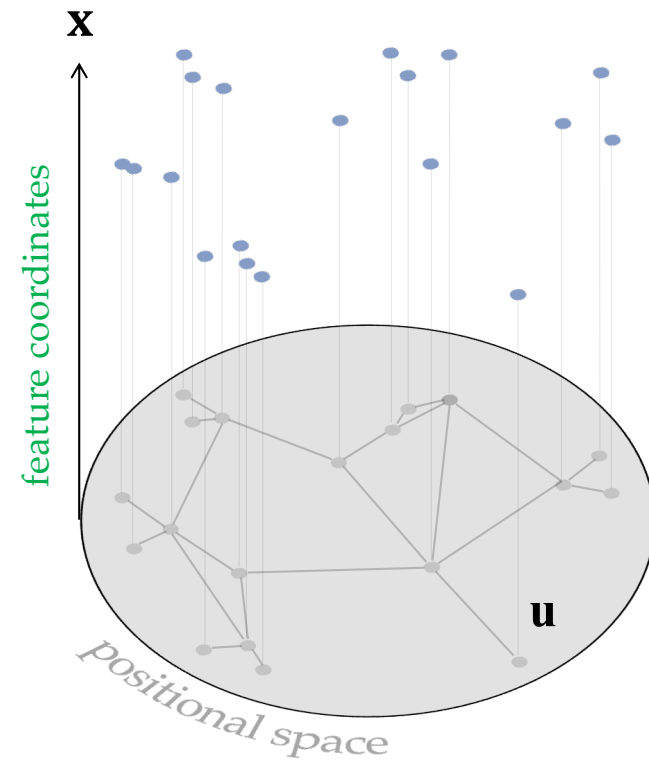


## Graph Beltrami flow

- Graph with positional and feature node coordinates  $\mathbf{z}_i = (\mathbf{u}_i, \mathbf{x}_i)$
- **Graph Beltrami flow**

$$\dot{\mathbf{z}}_i(t) = \sum_{j \in \mathcal{N}_i} a(\mathbf{z}_i(t), \mathbf{z}_j(t)) (\mathbf{z}_j(t) - \mathbf{z}_i(t))$$

- Evolution of  $\mathbf{x}$  = feature diffusion
- Evolution of  $\mathbf{u}$  = graph rewiring





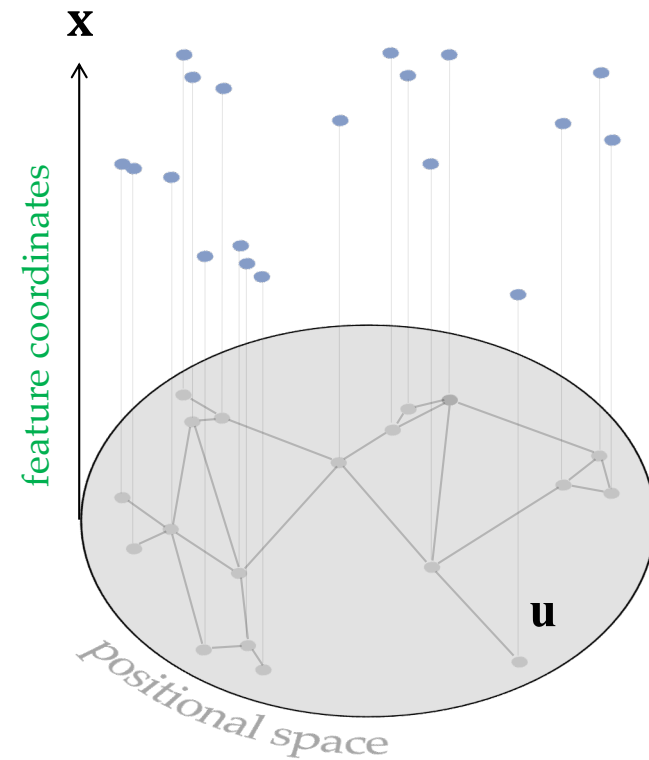
# Graph Beltrami flow

- Graph with positional and feature node coordinates  $\mathbf{z}_i = (\mathbf{u}_i, \mathbf{x}_i)$
- **Graph Beltrami flow**

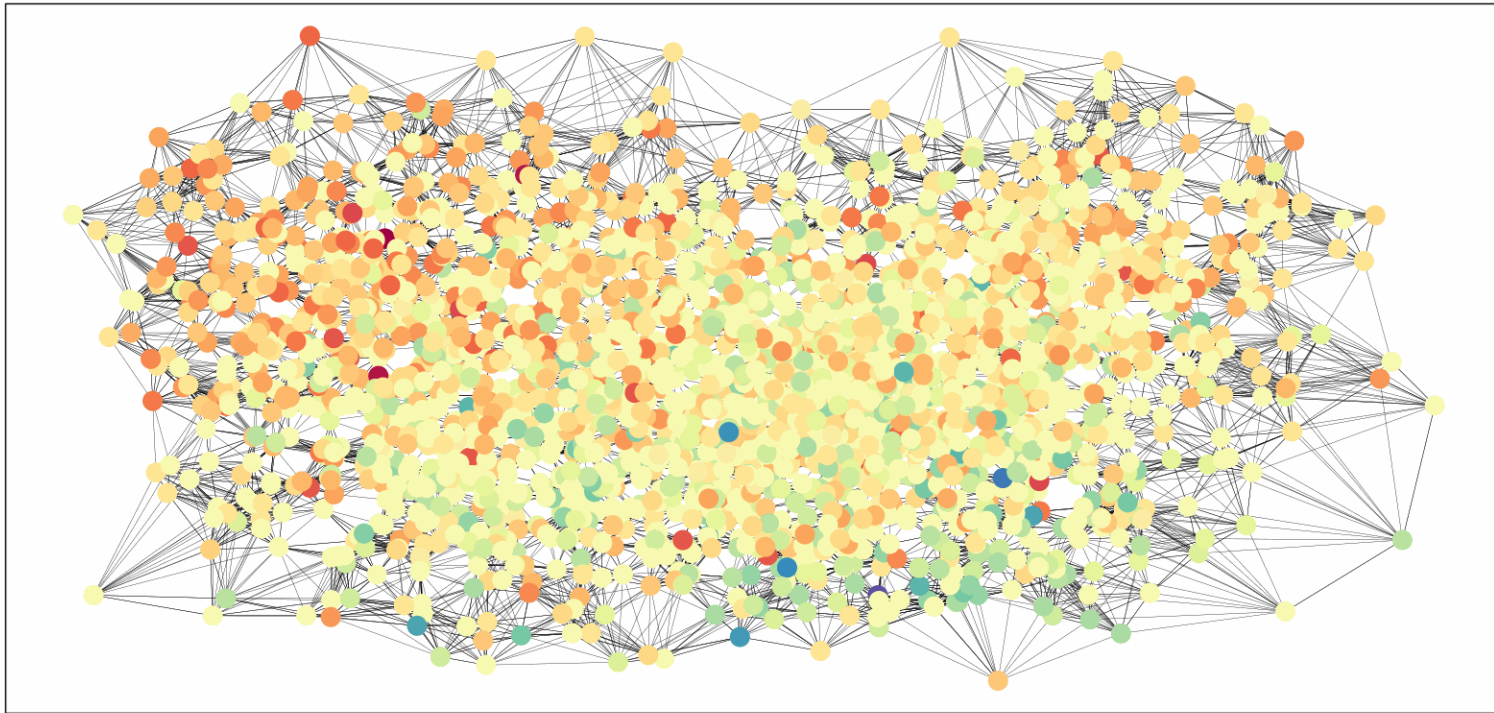
$$\dot{\mathbf{z}}_i(t) = \sum_{j \in \mathcal{N}'_i} a(\mathbf{z}_i(t), \mathbf{z}_j(t)) (\mathbf{z}_j(t) - \mathbf{z}_i(t))$$

*rewired graph*

- Evolution of  $\mathbf{x}$  = feature diffusion
- Evolution of  $\mathbf{u}$  = graph rewiring



## *Graph Beltrami flow*

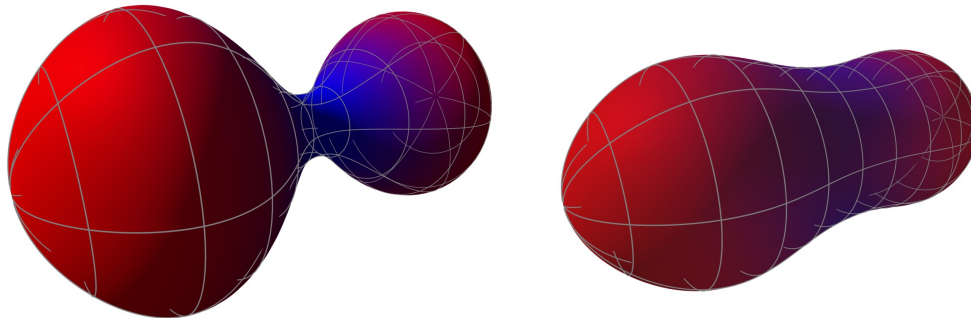


Evolution of positional/feature components + rewiring of the Cora graph

# Ricci flow

- **Ricci flow:** “diffusion of the Riemannian metric”

$$\frac{\partial g_{ij}}{\partial t} = R_{ij}$$



Evolution of a manifold under Ricci flow



**G. Ricci-Curbastro**



**R. Hamilton**

# Science

22 December 2006 | \$10

Breakthrough  
of the Year



The  
Poincaré  
Conjecture  
PROVED



G. Perelman



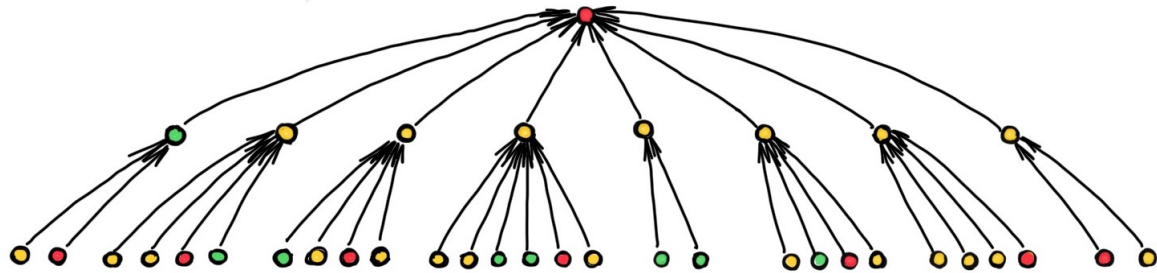
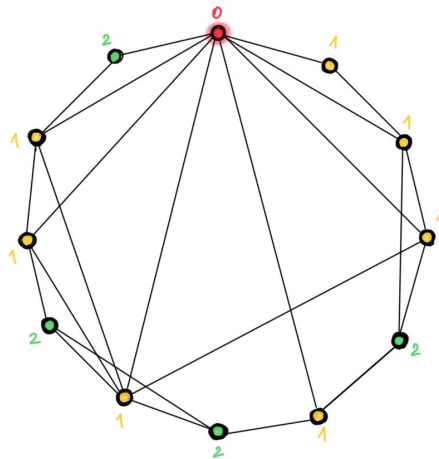
G. Ricci-Curbastro



R. Hamilton

Ricci 1903; Hamilton 1988; Perelman 2003

## Over-squashing & Bottlenecks



In small-world graphs metric ball volume  $\text{vol}(B_k) = \sum_{j \in B_k} d_j$   
grows exponentially with ball radius  $k$

Long-distance dependency + Fast volume growth  
= Over-squashing

# Over-squashing

- Consider an MPNN of the form

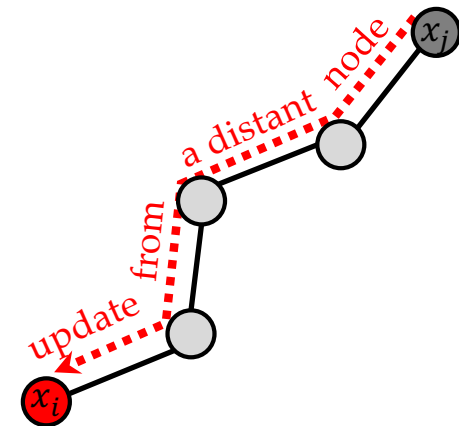
$$\mathbf{x}_i^{(k+1)} = \sigma \left( \mathbf{W}_1 \mathbf{x}_i^{(k)} + \sum_j a_{ij} \mathbf{W}_2 \mathbf{x}_j^{(k)} \right)$$

- $L = \text{depth}$  (number of layers)
- $p = \text{width}$  (hidden dimension)
- Nonlinearity  $\sigma$  is  $c_\sigma$ -Lipschitz-continuous
- $w = \text{maximum element of weight matrices } \mathbf{W}_1, \mathbf{W}_2$

**Theorem (Sensitivity bound):** For any  $i, j \in V$

$$\left\| \frac{\partial \mathbf{x}_i^{(L)}}{\partial \mathbf{x}_j^{(0)}} \right\|_1 \leq (c_\sigma w p)^L (\mathbf{I} + \mathbf{A})_{ij}^L$$

Topping, Di Giovanni et B 2021; Di Giovanni et B 2023



**Over-squashing:** small Jacobian  $\left\| \partial \mathbf{x}_i^{(L)} / \partial \mathbf{x}_j^{(0)} \right\|$  indicates poor information propagation from input node

# Over-squashing

- Consider an MPNN of the form

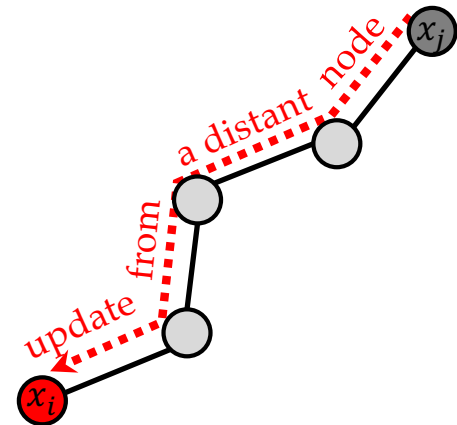
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Topping, Di Giovanni et B 2021; Di Giovanni et B 2023



**Over-squashing:** small Jacobian  $\left\| \frac{\partial \mathbf{x}_i^{(L)}}{\partial \mathbf{x}_j^{(0)}} \right\|$  indicates poor information propagation from input node

## Preventing over-squashing

$$\left\| \frac{\partial \mathbf{x}_i^{(L)}}{\partial \mathbf{x}_j^{(0)}} \right\|_1 \leq (\underbrace{c_\sigma w p}_{\text{model}})^L (\mathbf{I} + \mathbf{A})_{ij}^L$$

model topology

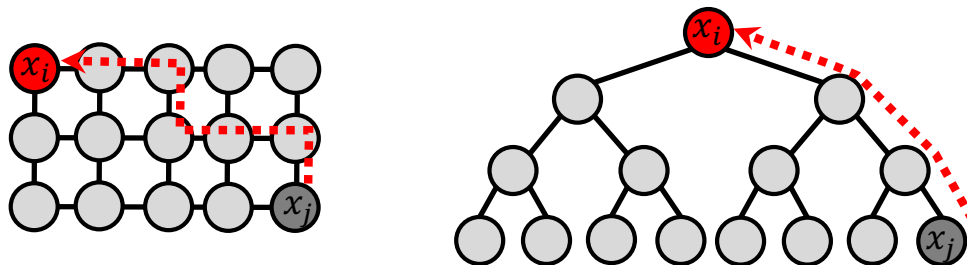
- **Width**  $p$  helps mitigate over-squashing (potentially at the risk of worse generalization)
- **Depth**  $L$  **does not** help
  - If  $L \sim \text{diam}(G)$ , over-squashing occurs between distant nodes
  - If  $L \gg 1$ , we transition from over-squashing to vanishing gradients



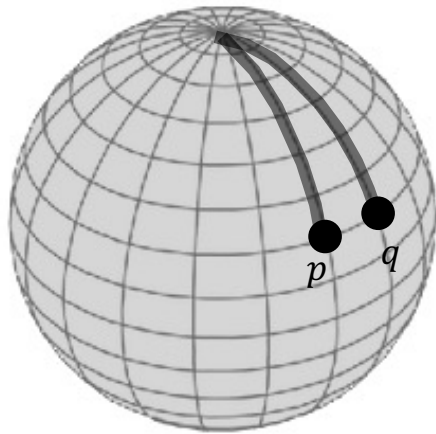
# Preventing over-squashing

$$\left\| \frac{\partial \mathbf{x}_i^{(L)}}{\partial \mathbf{x}_j^{(0)}} \right\|_1 \leq \underbrace{(c_\sigma w p)^L}_{\text{model}} \underbrace{(\mathbf{I} + \mathbf{A})^L}_{\text{topology}}_{ij}$$

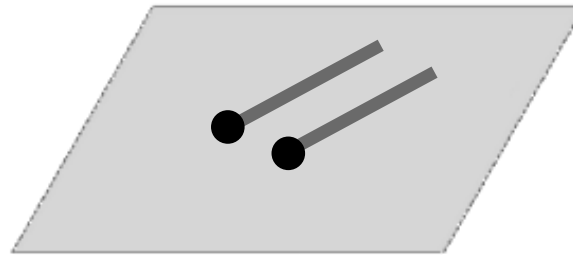
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  - If  $L \sim \text{diam}(G)$ , over-squashing occurs between distant nodes
  - If  $L \gg 1$ , we transition from over-squashing to vanishing gradients
- **Topology** of  $G$  has the largest effect on over-squashing



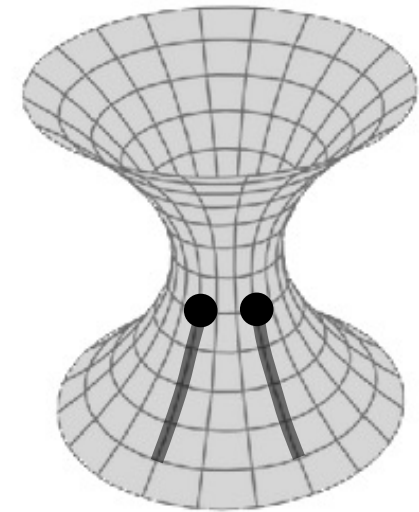
# *Ricci Curvature on Manifolds*



Spherical ( $>0$ )



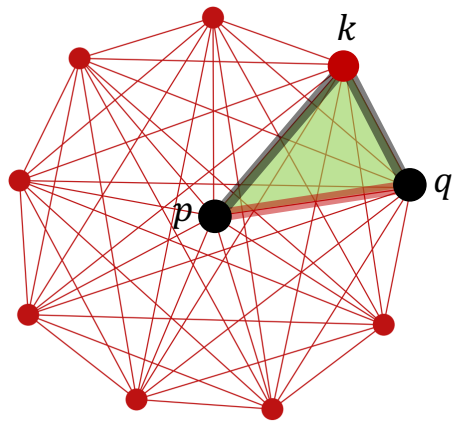
Euclidean ( $=0$ )



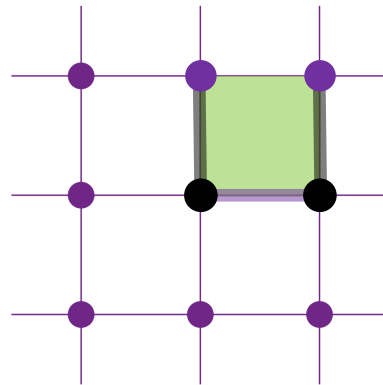
Hyperbolic ( $<0$ )

**“geodesic dispersion”**

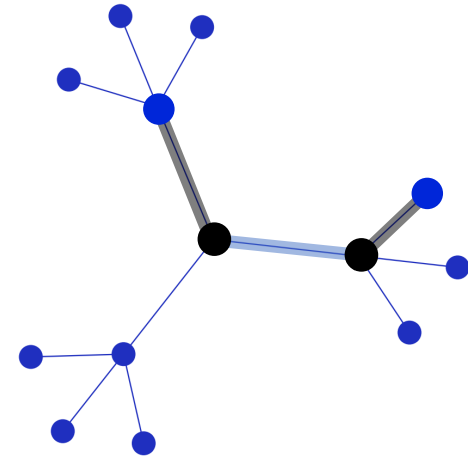
# Ricci Curvature on Graphs



Clique ( $>0$ )



Grid ( $=0$ )



Tree ( $<0$ )

# Balanced Forman Curvature

**Balanced Forman Curvature** of edge  $i \sim j$  in simple unweighted graph  $\text{Ric}(i, j) = 0$  if  $\min\{d_i, d_j\} = 1$  and otherwise

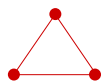
$$\text{Ric}(i, j) = \frac{2}{d_i} + \frac{2}{d_j} + 2 \frac{|\#_{\Delta}(i, j)|}{\max\{d_i, d_j\}} + \frac{|\#_{\Delta}(i, j)|}{\min\{d_i, d_j\}} + \frac{\gamma_{\max}^{-1}}{\max\{d_i, d_j\}} (|\#_{\square}^i(i, j)| + |\#_{\square}^j(i, j)|) - 2$$

*Degree of i* (pointing to  $d_i$ )  
*Triangles based at  $i \sim j$*  (pointing to  $|\#_{\Delta}(i, j)|$ )  
*Max number of 4-cycle based at  $i \sim j$  traversing the same node* (pointing to  $\gamma_{\max}^{-1}$ )  
*Neighbours of i forming a 4-cycle based at  $i \sim j$  (w/o diagonals)* (pointing to  $|\#_{\square}^i(i, j)|$ )

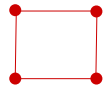
# Balanced Forman Curvature

**Balanced Forman Curvature** of edge  $i \sim j$  in simple unweighted graph  $\text{Ric}(i, j) = 0$  if  $\min\{d_i, d_j\} = 1$  and otherwise

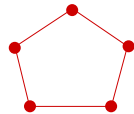
$$\text{Ric}(i, j) = \frac{2}{d_i} + \frac{2}{d_j} + 2 \frac{|\#_{\Delta}(i, j)|}{\max\{d_i, d_j\}} + \frac{|\#_{\Delta}(i, j)|}{\min\{d_i, d_j\}} + \frac{\gamma_{\max}^{-1}}{\max\{d_i, d_j\}} (|\#_{\square}^i(i, j)| + |\#_{\square}^j(i, j)|) - 2$$



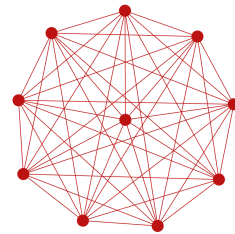
Cycle  $C_3$ :  $\frac{3}{2}$



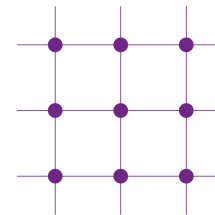
$C_4$ : 1



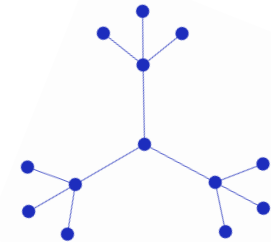
$C_{n \geq 5}$ : 0



Clique  $K_n$ :  $\frac{n}{n-1}$



Grid  $G_n$ : 0



Tree  $T_r$ :  $\frac{4}{r+1} - 2$

## Over-squashing & Bottleneck via Curvature

**Theorem 1 (main result):** Consider an MPNN with  $L \geq 2$  layers and  $|\nabla\phi_\ell| \leq \alpha$  and  $|\nabla\psi_\ell| \leq \beta$ . Let  $i \sim j$  with  $d_i \leq d_j$  and assume  $\exists \delta$  s.t.  $0 < \delta < \max\{d_i, d_j\}^{1/2}$ ,  $\delta < \gamma_{\max}^{-1}$  and  $\text{Ric}(i, j) \leq -2 + \delta$ . Then, there exist nodes  $Q \subset \{s: d_G(i, s) = 2\}$  of size  $|Q| > 1/\delta$  s.t.

Small  $\delta =$   
negative curvature

$$\frac{1}{|Q|} \sum_{k \in Q} \left| \frac{\partial x_k^{(\ell+2)}}{\partial x_i^{(\ell)}} \right| < (\alpha\beta)^2 \delta^{1/4}$$

more nodes

stronger over-squashing

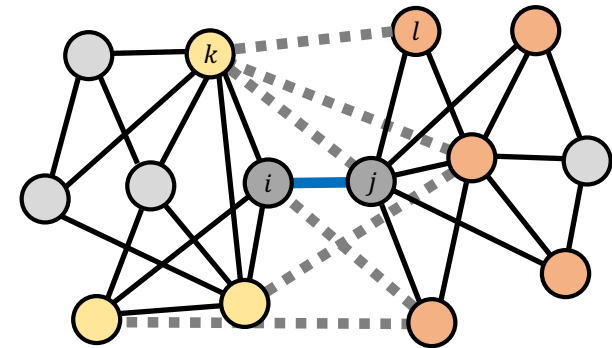
**Over-squashing is caused by strongly  
negatively-curved edges!**

# Stochastic Discrete Ricci Flow (SDRF)

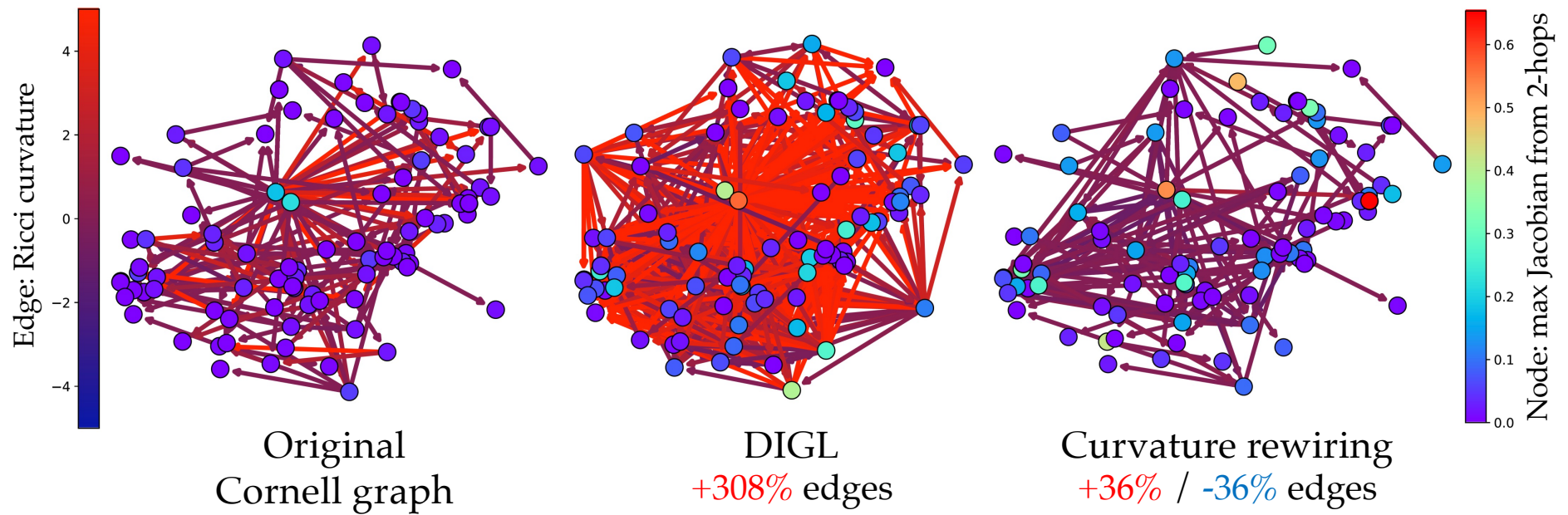
**Input:** graph  $G = (V, E)$ , temperature  $\tau > 0$ , (optional  $C$ )

- For edge  $i \sim j$  with smallest  $\text{Ric}(i, j)$ 
  - Calculate the improvement  $\delta_{kl} = \text{Ric}_{G'}(i, j) - \text{Ric}(i, j)$  from adding edge  $k \sim l$  with  $k \in B_1(i)$  and  $l \in B_1(j)$
  - Sample index  $k, l$  with probability  $\text{Softmax}(\tau \delta_{kl})$  and add edge  $k \sim l$  to  $E'$
- (optional) Remove edge  $i \sim j$  with largest  $\text{Ric}(i, j) > C$

**Output:** new graph  $G' = (V, E')$



# Curvature- vs Diffusion-based Rewiring

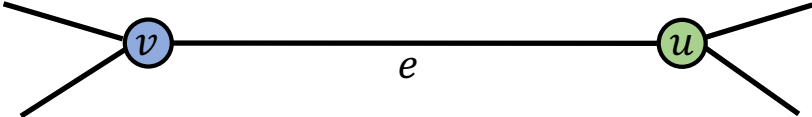




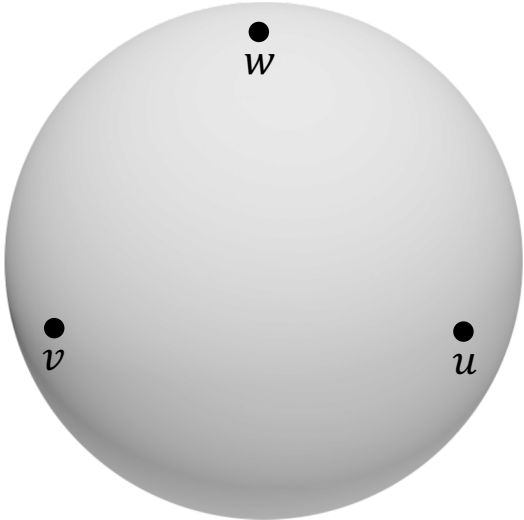


Even more Exotic Stuff

# Cellular Sheaves

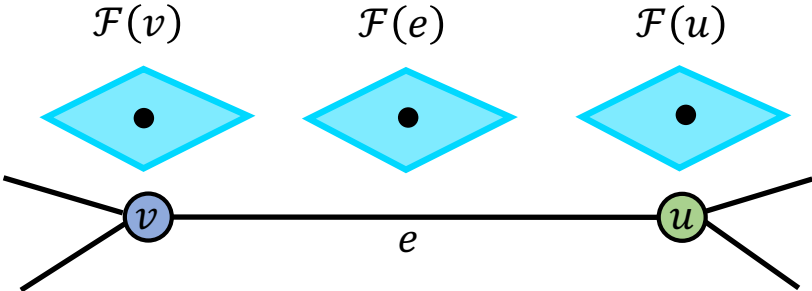


Graph

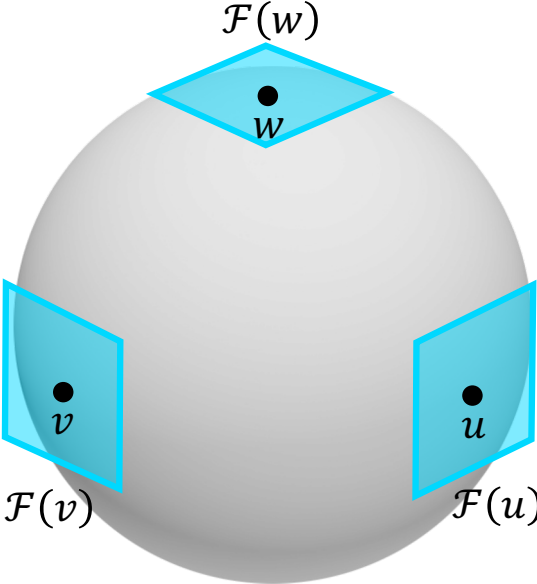


Manifold

# Cellular Sheaves

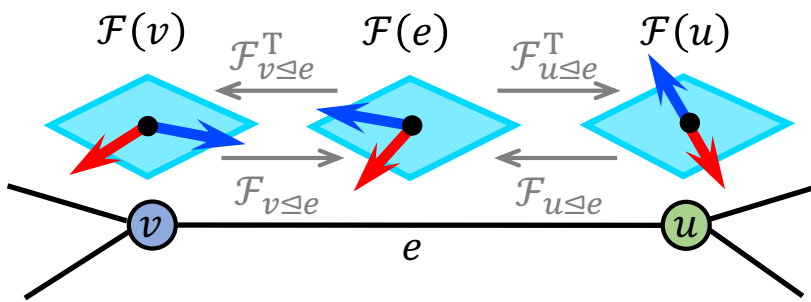


Cellular sheaf  $\mathcal{F}$

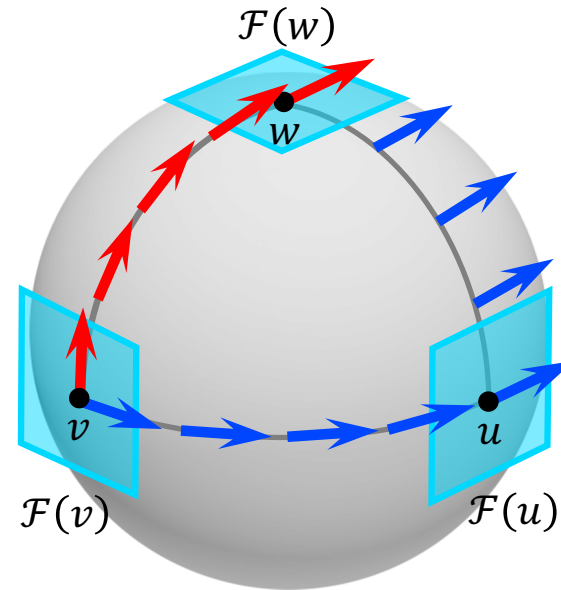


Manifold + Connection

# Cellular Sheaves



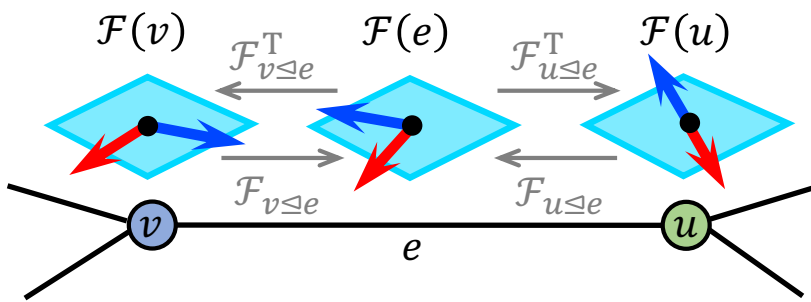
Cellular sheaf  $\mathcal{F}$



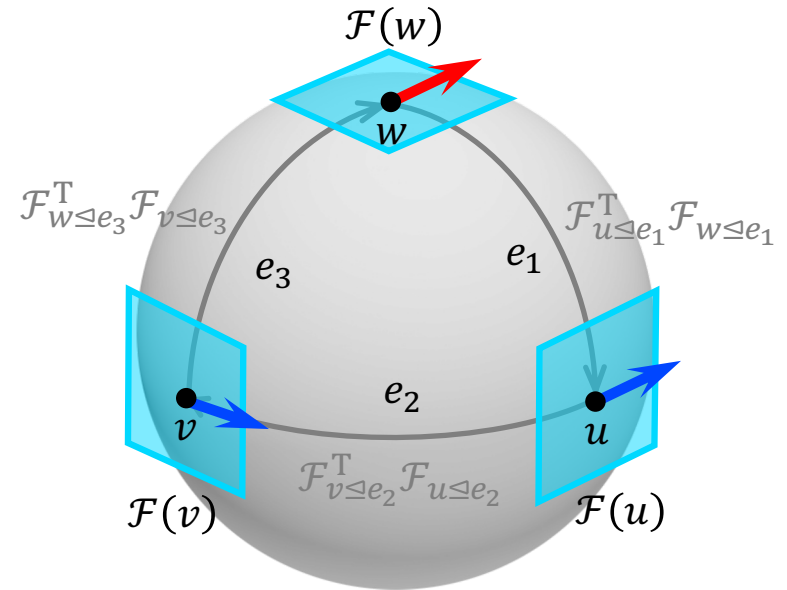
Manifold + Connection



# Cellular Sheaves

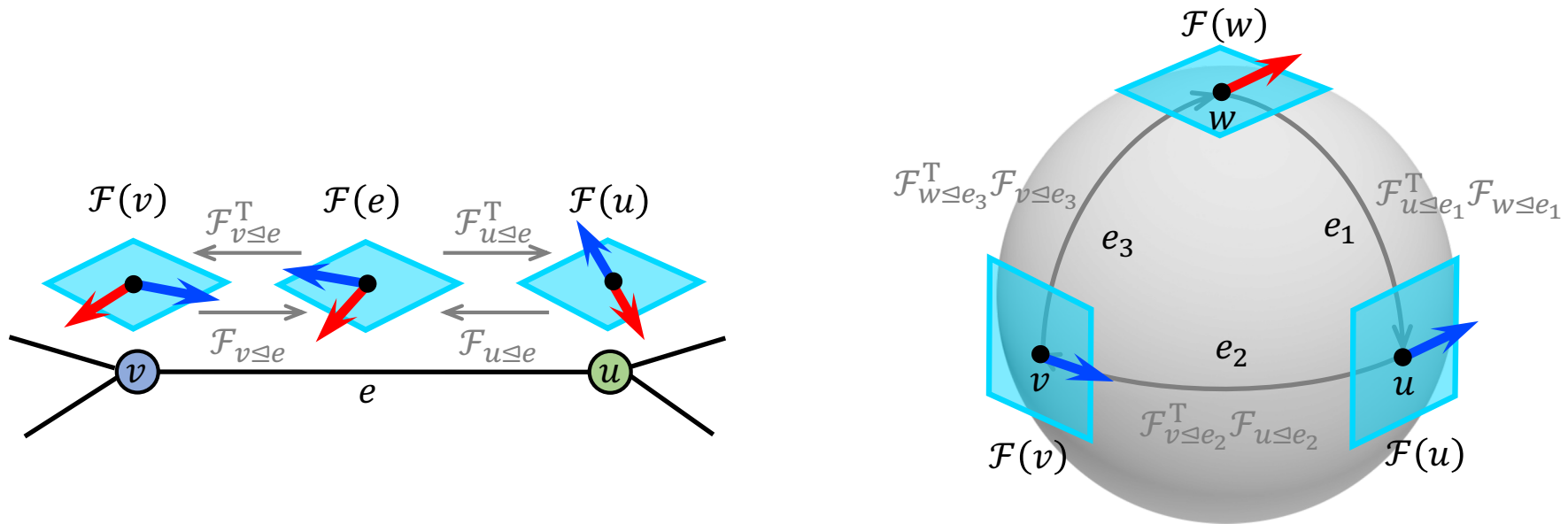


Cellular sheaf  $\mathcal{F}$



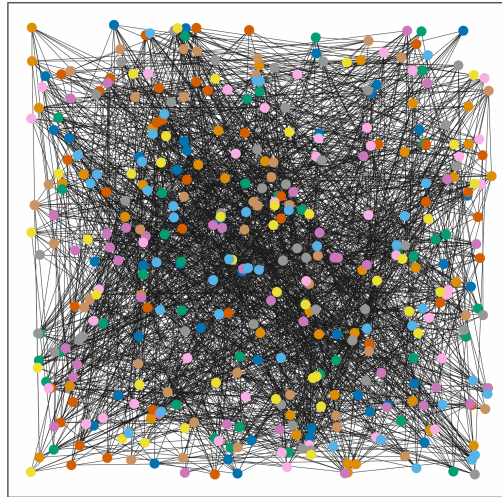
Analogy to parallel transport on manifolds

# Cellular Sheaves



Endow graph with "geometry" leading to richer diffusion with better separation, ability to cope with heterophily, and no oversmoothing

## *Diffusion on Cellular Sheaves*



$$\dot{\mathbf{X}}(t) = \Delta_{\mathcal{F}} \mathbf{X}(t) \quad \text{with i.c. } \mathbf{X}(0) = \mathbf{X}$$

Node classification = limit of sheaf diffusion equation  
with an appropriate sheaf

## *Alternative to Weisfeiler-Lehman for expressive power?*

<b>Graph type</b>	<b># Node classes</b>	<b>Sheaf class <math>\mathcal{F}</math>, <math>\dim=d</math></b>	
Homophilic	2	Symmetric $d=1$	✓
Heterophilic	2	Symmetric $d=1$	✗
	2	Non-symmetric $d=1$	✓
	$\geq 3$	Non-symmetric $d=1$	✗
	$\leq 2d$	Orthogonal, $d=\{2,4\}$	✓

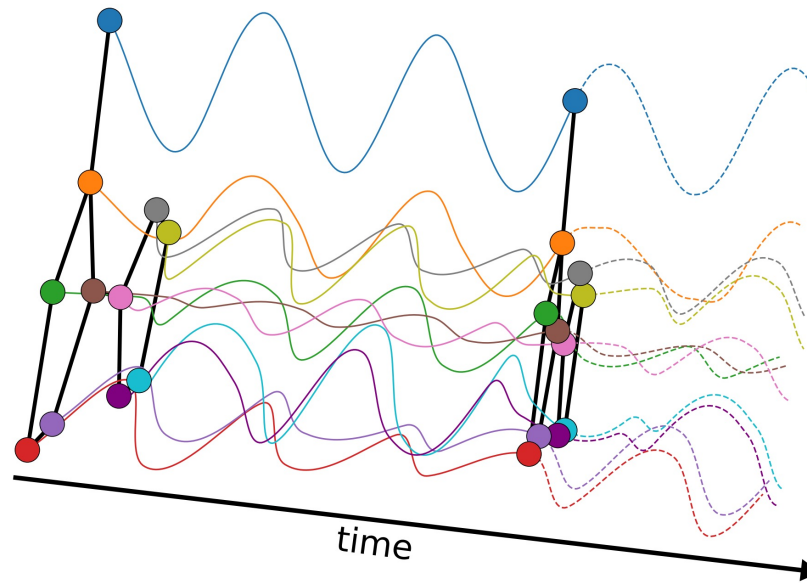
The capability of sheaf diffusion to solve node classification problem in the limit



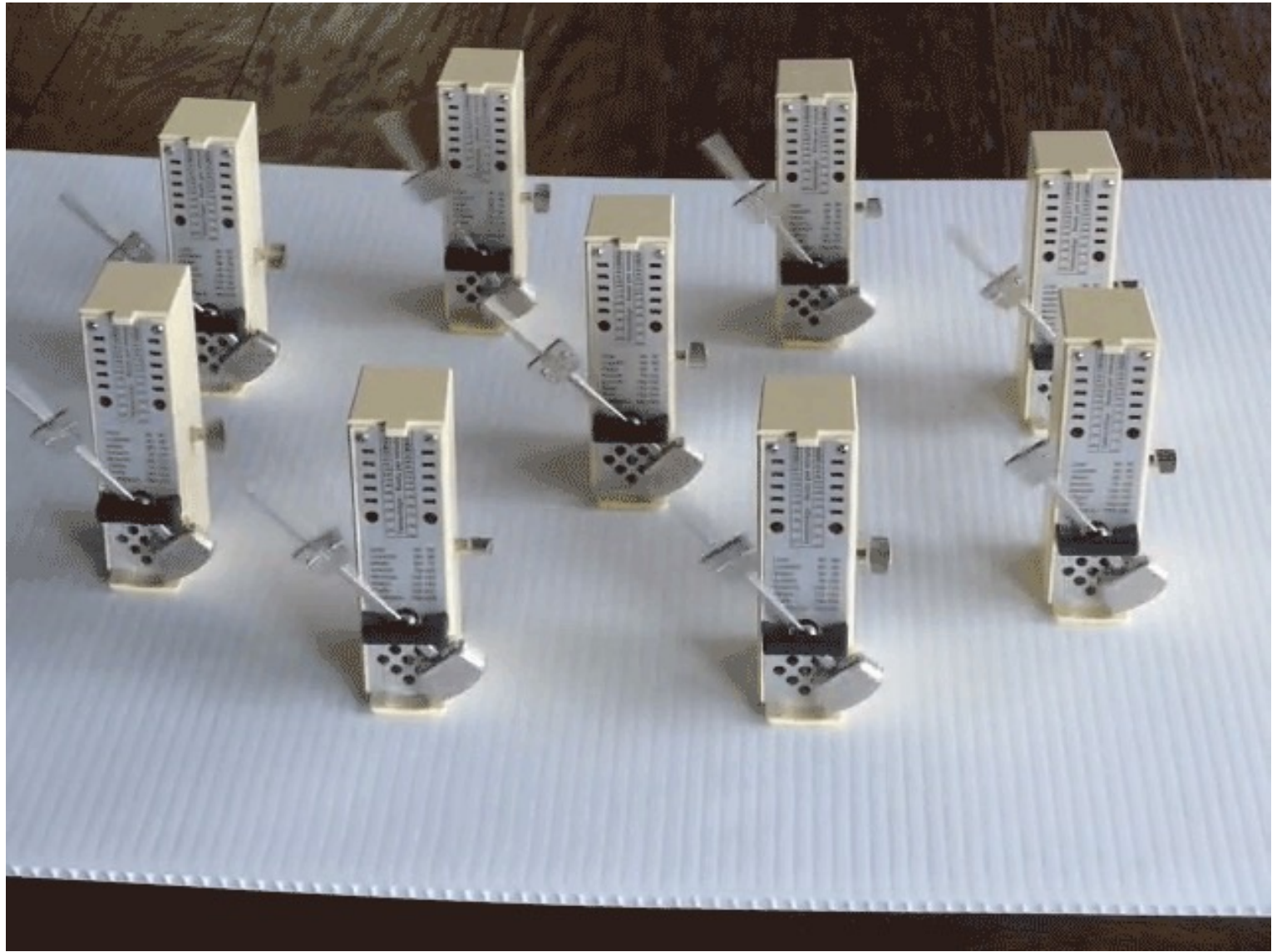
## *What do we gain from physics-inspired GNNs?*

- New perspectives on old problems (e.g. oversmoothing, bottlenecks, etc.)
- New architectures
  - Many GNNs can be formalised as a discretised Graph Diffusion equation
  - More efficient solvers (multistep, adaptive, implicit, multigrid, etc.)
  - Implicit schemes = multi-hop filters
- Principled architectural choices (residual connection, shared symmetric weights)
- Theoretical guarantees (e.g. stability, convergence, expressive power, etc.)
- Deep links to other fields less known in GNN literature (e.g. differential geometry and algebraic topology)
- Other physical models

# Graph-Coupled Oscillators



Dynamics of a system of coupled oscillators on a molecular graph





Thank you!